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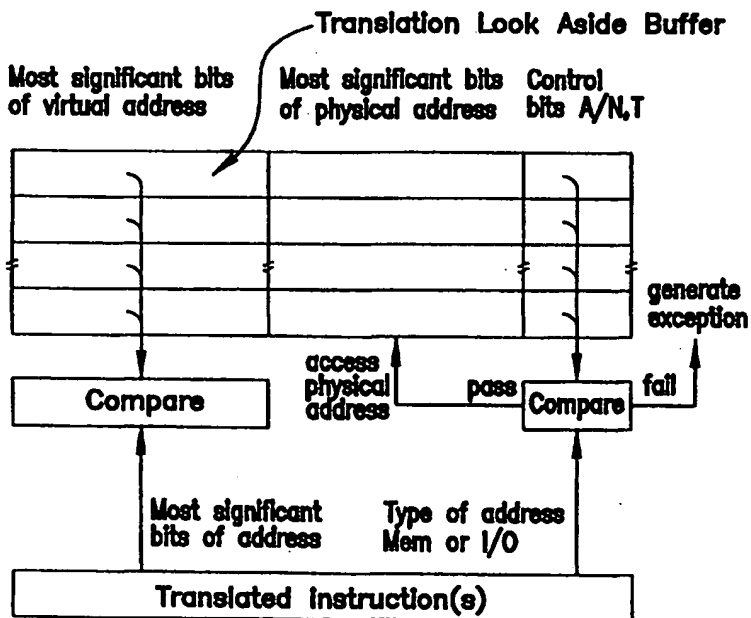
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(54) Title: A MEMORY CONTROLLER FOR DETECTING A FAILURE OF SPECULATION OF A COMPONENT BEING ADDRESSED



(57) Abstract

A memory controller for a microprocessor including apparatus to both detect a failure of speculation on the nature of the memory being addressed, and apparatus to recover from such failures.

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A Memory Controller for Detecting a Failure of Speculation of a Component Being Addressed

BACKGROUND OF THE INVENTION

Field Of The Invention

5 This invention relates to computer systems and, more particularly, to methods and apparatus for providing an improved microprocessor.

History Of The Prior Art

There are thousands of application programs which run on computers designed around particular families of microprocessors. The largest
10 number of programs in existence are designed to run on computers (generally referred to as "IBM Compatible Personal Computers") using the "X86" family of microprocessors (including the Intel[®] 8088, Intel 8086, Intel 80186, Intel 80286, i386, i486, and progressing through the various Pentium[®] microprocessors) designed and manufactured by
15 Intel Corporation of Santa Clara, California. There are many other examples of programs designed to run on computers using other families of processors. Because there are so many application programs which run on these computers, there is a large market for microprocessors capable of use in such computers, especially
20 computers designed to process X86 programs. The microprocessor market is not only large but also quite lucrative.

Although the market for microprocessors which are able to run large numbers of application programs is large and lucrative, it is quite difficult to design a new competitive microprocessor. For example,
25 even though the X86 family of processors has been in existence for a number of years and these processors are included in the majority of

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computers sold and used, there are few successful competitive microprocessors which are able to run X86 programs. The reasons for this are many.

In order to be successful, a microprocessor must be able to run all of the programs (including operating systems and legacy programs) designed for that family of processors as fast as existing processors without costing more than existing processors. In addition, to be economically successful, a new microprocessor must do at least one of these things better than existing processors to give buyers a reason to choose the new processor over existing proven processors.

It is difficult and expensive to make a microprocessor run as fast as state of the art microprocessors. Processors carry out instructions through primitive operations such as loading, shifting, adding, storing, and similar low level operations and respond only to such primitive instructions in executing any instruction furnished by an application program. For example, a processor designed to run the instructions of a complicated instruction set computer (CISC) such as a X86 in which instructions may designate the process to be carried out at a relatively high level have historically included read only memory (ROM) which stores so-called micro-instructions. Each micro-instruction includes a sequence of primitive instructions which when run in succession bring about the result commanded by the high level CISC instruction. Typically, an "add A to B" CISC instruction is decoded to cause a look up of an address in ROM at which a micro-instruction for carrying out the functions of the "add A to B" instruction is stored. The micro-instruction is loaded, and its primitive instructions are run in sequence to cause the "add A to B"

instruction to be carried out. With such a CISC computer, the primitive operations within a micro-instruction can never be changed during program execution. Each CISC instruction can only be run by decoding the instruction, addressing and fetching the micro-
5 instruction, and running the sequence of primitive operations in the order provided in the micro-instruction. Each time the micro-instruction is run, the same sequence must be followed.

State of the art processors for running X86 applications utilize a number of techniques to provide the fastest processing possible at a price which is still economically reasonable. Any new processor which
10 implements known hardware techniques for accelerating the speed at which a processor may run must increase the sophistication of the processing hardware. This requires increasing the cost of the hardware.

15 For example, a superscalar microprocessor which uses a plurality of processing channels in order to execute two or more operations at once has a number of additional requirements. At the most basic level, a simple superscalar microprocessor might decode each application instruction into the micro-instructions which carry out the
20 function of the application instruction. Then, the simple superscalar microprocessor schedules two micro-instructions to run together if the two micro-instructions do not require the same hardware resources and the execution of a micro-instruction does not depend on the results of other micro-instructions being processed.

25 A more advanced superscalar microprocessor typically decodes each application instruction into a series of primitive instructions so that

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those primitive instructions may be reordered and scheduled into the most efficient execution order. This requires that each individual primitive operation be addressed and fetched. To accomplish reordering, the processor must be able to ensure that a primitive instruction which requires data resulting from another primitive instruction is run after that other primitive instruction produces the needed data. Such a superscalar microprocessor must assure that two primitive instructions being run together do not both require the same hardware resources. Such a processor must also resolve conditional branches before the effects of branch operations can be completed.

Thus, superscalar microprocessors require extensive hardware to compare the relationships of the primitive instructions to one another and to reorder and schedule the sequence of the primitive instructions to carry out any instruction. As the number of processing channels increases, the amount and cost of the hardware to accomplish these superscalar acceleration techniques increases approximately quadratically. All of these hardware requirements increase the complexity and cost of the circuitry involved. As in dealing with micro-instructions, each time an application instruction is executed, a superscalar microprocessor must use its relatively complicated addressing and fetching hardware to fetch each of these primitive instructions, must reorder and reschedule these primitive instructions based on the other primitive instructions and hardware usage, and then must execute all of the rescheduled primitive instructions. The need to run each application instruction through the entire hardware

sequence each time it is executed limits the speed at which a superscalar processor is capable of executing its instructions.

Moreover, even though these various hardware techniques increase the speed of processing, the complexity involved in providing such hardware significantly increases the cost of such a microprocessor. For example, the Intel i486 DX4 processor uses approximately 1.5 million transistors. Adding the hardware required to accomplish the checking of dependencies and scheduling necessary to process instructions through two channels in a basic superscalar microprocessor such as the Intel Pentium® requires the use of more than three million transistors. Adding the hardware to allow reordering among primitive instructions derived from different target instructions, provide speculative execution, allow register renaming, and provide branch prediction increases the number of transistors to over six million in the Intel Pentium Pro™ microprocessor. Thus, it can be seen that each hardware addition to increase operation speed has drastically increased the number of transistors in the latest state of the art microprocessors.

Even using these known techniques may not produce a microprocessor faster than existing microprocessors because manufacturers use most of the economically feasible techniques known to accelerate the operation of existing microprocessors. Consequently, designing a faster processor is a very difficult and expensive task.

Reducing the cost of a processor is also very difficult. As illustrated above, hardware acceleration techniques which produce a sufficiently

capable processor are very expensive. One designing a new processor must obtain the facilities to produce the hardware. Such facilities are very difficult to obtain because chip manufacturers do not typically spend assets on small runs of devices. The capital investment
5 required to produce a chip manufacturing facility is so great that it is beyond the reach of most companies.

Even though one is able to design a new processor which runs all of the application programs designed for a family of processors at least as fast as competitive processors, the price of competitive processors
10 includes sufficient profit that substantial price reductions are sure to be faced by any competitor.

Although designing a competitive processor by increasing the complexity of the hardware is very difficult, another way to run application programs (target application programs) designed for a
15 particular family of microprocessors (target microprocessors) has been to emulate the target microprocessor in software on another faster microprocessor (host microprocessor). This is an incrementally inexpensive method of running these programs because it requires only the addition of some form of emulation software which enables
20 the application program to run on a faster microprocessor. The emulator software changes the target instructions of an application program written for the target processor family into host instructions capable of execution by the host microprocessor. These changed instructions are then run under control of the operating system on the
25 faster host microprocessor.

There have been a number of different designs by which target applications may be run on host computers with faster processors than the processors of target computers. In general, the host computers executing target programs using emulation software utilize
5 reduced instruction set (RISC) microprocessors because RISC processors are theoretically simpler and consequently can run faster than other types of processors.

However, even though RISC computer systems running emulator software are often capable of running X86 (or other) programs, they
10 usually do so at a rate which is substantially slower than the rate at which state of the art X86 computer systems run the same programs. Moreover, often these emulator programs are not able to run all or a large number of the target programs available.

The reasons why emulator programs are not able to run target
15 programs as rapidly as the target microprocessors is quite complicated and requires some understanding of the different emulation operations. Figure 1 includes a series of diagrams representing the different ways in which a plurality of different types of microprocessors execute target application programs.

20 In Figure 1(a), a typical CISC microprocessor such as an Intel X86 microprocessor is shown running a target application program which is designed to be run on that target processor. As may be seen, the application is run on the CISC processor using a CISC operating system (such as MS DOS, Windows 3.1, Windows NT, and OS/2
25 which are used with X86 computers) designed to provide interfaces by which access to the hardware of the computer may be gained.

Typically, the instructions of the application program are selected to utilize the devices of the computer only through the access provided by the operating system. Thus, the operating system handles the manipulations which allow applications access to memory and to the various input/output devices of the computer. The target computer includes memory and hardware which the operating system recognizes, and a call to the operating system from a target application causes an operating system device driver to cause an expected operation to occur with a defined device of the target computer. The instructions of the application execute on the processor where they are changed into operations (embodied in microcode or the more primitive operations from which microcode is assembled) which the processor is capable of executing. As has been described above, each time a complicated target instruction is executed, the instruction calls the same subroutine stored as microcode (or as the same set of primitive operations). The same subroutine is always executed. If the processor is a superscalar, these primitive operations for carrying out a target instruction can often be reordered by the processor, rescheduled, and executed using the various processing channels in the manner described above; however, the subroutine is still fetched and executed.

In Figure 1(b), a typical RISC microprocessor such as a PowerPC microprocessor used in an Apple Macintosh computer is represented running the same target application program which is designed to be run on the CISC processor of Figure 1(a). As may be seen, the target application is run on the host processor using at least a partial target operating system to respond to a portion of the calls which the target

application generates. Typically these are calls to the application-like portions of the target operating system used to provide graphical interfaces on the display and short utility programs which are generally application-like. The target application and these portions of the target operating system are changed by a software emulator such as Soft PC[®] which breaks the instructions furnished by the target application program and the application-like target operating system programs into instructions which the host processor and its host operating system are capable of executing. The host operating system provides the interfaces through which access to the memory and input/output hardware of the RISC computer may be gained.

However, the host RISC processor and the hardware devices associated with it in a host RISC computer are usually quite different than are the devices associated with the processor for which the target application was designed; and the various instructions provided by the target application program are designed to cooperate with the device drivers of the target operating system in accessing the various portions of the target computer. Consequently, the emulation program, which changes the instructions of the target application program to primitive host instructions which the host operating system is capable of utilizing, must somehow link the operations designed to operate hardware devices in the target computer to operations which hardware devices of the host system are capable of implementing. Often this requires the emulator software to create virtual devices which respond to the instructions of the target application to carry out operations which the host system is incapable of carrying out because the target devices are not those of the host

computer. Sometimes the emulator is required to create links from these virtual devices through the host operating system to host hardware devices which are present but are addressed in a different manner by the host operating system.

5 Target programs when executed in this manner run relatively slowly for a number of reasons. First, each target instruction from a target application program and from the target operating system must be changed by the emulator into the host primitive functions used by the host processor. If the target application is designed for a CISC
10 machine such as an X86, the target instructions are of varying lengths and quite complicated so that changing them to host primitive instructions is quite involved. The original target instructions are first decoded, and the sequence of primitive host instructions which make up the target instructions are determined. Then the address (or
15 addresses) of each sequence of primitive host instructions is determined, each sequence of the primitive host instructions is fetched, and these primitive host instructions are executed in or out of order. The large number of extra steps required by an emulator to change the target application and operating system instructions into
20 host instructions understood by the host processor must be conducted each time an instruction is executed and slows the process of emulation.

Second, many target instructions include references to operations conducted by particular hardware devices which function in a
25 particular manner in the target computer, hardware which is not available in the host computer. To carry out the operation, the emulation software must either make software connections to the

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hardware devices of the host computer through the existing host operating system or the emulator software must furnish a virtual hardware device. Emulating the hardware of another computer in software is very difficult. The emulation software must generate
5 virtual devices for each of the target application calls to the host operating system; and each of these virtual devices must provide calls to the actual host devices. Emulating a hardware device requires that when a target instruction is to use the device, the code representing the virtual device required by that instruction be fetched from memory
10 and run to implement the device. Either of these methods of solving the problem adds another series of operations to the execution of the sequence of instructions.

Complicating the problem of emulation is the requirement that the target application take various exceptions which are carried out by
15 hardware of the target computer and the target operating system in order for the computer system to operate. When a target exception is taken during the operation of a target computer, state of the computer at the time of the exception must be saved typically by calling a microcode sequence to accomplish the operation, the correct exception
20 handler must be retrieved, the exception must be handled, then the correct point in the program must be found for continuing with the program. Sometimes this requires that the program revert to the state of the target computer at the point the exception was taken, and at other times a branch provided by the exception handler is taken. In
25 any case, the hardware and software of the target computer required to accomplish these operations must somehow be provided in the process of emulation. Because the correct target state must be

available at the time of any such exception for proper execution, the emulator is forced to keep accurate track of this state at all times so that it is able to correctly respond to these exceptions. In the prior art, this has required executing each instruction in the order provided
5 by the target application because only in this way could correct target state be maintained.

Moreover, prior art emulators have always been required to maintain the order of execution of the target application for other reasons. Target instructions can be of two types, ones which affect memory or
10 ones which affect a memory mapped input/output (I/O) device. There is no way to know without attempting to execute an instruction whether an operation is to affect memory or a memory-mapped I/O device. When instructions operate on memory, optimizing and reordering is possible and greatly aids in speeding the operation of a
15 system. However, operations affecting I/O devices often must be practiced in the precise order in which those operations are programmed without the elimination of any steps or they may have some adverse effect on the operation of the I/O device. For example, a particular I/O operation may have the effect of clearing an I/O
20 register. If the operations take place out of order so that a register is cleared of a value which is still necessary, then the result of the operation may be different than the operation commanded by the target instruction. Without a means to distinguish memory from memory mapped I/O, it is necessary to treat all instructions as
25 though they affect memory mapped I/O. This severely restricts the nature of optimizations that are achievable. Because prior art emulators lack both means to detect the nature of the memory being

addressed and means to recover from such failures, they are required to proceed sequentially through the target instructions as though each operation affects memory mapped I/O. This greatly limits the possibility of optimizing the host instructions.

- 5 Another problem which limits the ability of prior art emulators to optimize the host code is caused by self-modifying code. If a target instruction has been changed to a sequence of host instructions which in turn write back to change the original target instruction, then the host instructions are no longer valid. Consequently, the
10 emulator must constantly check to determine whether a store is to the target code area. All of these problems make this type of emulation much slower than running a target application on a target processor.

Another example of the type of emulation software shown in figure 1(b) is described in an article entitled, "Talisman: Fast and Accurate
15 Multicomputer Simulation," R. C. Bedichek, Laboratory for Computer Sciences, Massachusetts Institute of Technology. This is a more complete example of translation in that it can emulate a complete research system and run the research target operating system. Talisman uses a host UNIX operating system.

- 20 In Figure 1(c), another example of emulation is shown. In this case, a PowerPC microprocessor used in an Apple Macintosh computer is represented running a target application program which was designed to be run on the Motorola 68000 family CISC processors used in the original Macintosh computers; this type of arrangement has been
25 required in order to allow Apple legacy programs to run on the Macintosh computers with RISC processors. As may be seen, the

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target application is run on the host processor using at least a partial target operating system to respond to the application-like portions of the target operating system. A software emulator breaks the instructions furnished by the target application program and the application-like target operating system programs into instructions which the host processor and its host operating system are capable of executing. The host operating system provides the interfaces through which access to the memory and input/output hardware of the host computer may be gained.

- Again, the host RISC processor and the devices associated with it in the host RISC computer are quite different than are the devices associated with the Motorola CISC processor; and the various target instructions are designed to cooperate with the target CISC operating system in accessing the various portions of the target computer.
- Consequently, the emulation program must link the operations designed to operate hardware devices in the target computer to operations which hardware devices of the host system are capable of implementing. This requires the emulator to create software virtual devices which respond to the instructions of the target application and to create links from these virtual devices through the host operating system to host hardware devices which are present but are addressed in a different manner by the host operating system.

- The target software run in this manner runs relatively slowly for the same reasons that the emulation of Figure 1(b) runs slowly. First, each target instruction from the target application and from the target operating system must be changed by fetching the instruction; and all of the host primitive functions derived from that instruction must be

run in sequence each time the instruction is executed. Second, the emulation software must generate virtual devices for each of the target application calls to the host operating system; and each of these virtual devices must provide calls to the actual host devices. Third, the emulator must treat all instructions as conservatively as it treats instructions which are directed to memory mapped I/O devices or risk generating exceptions from which it cannot recover. Finally, the emulator must maintain the correct target state at all times and store operations must always check ahead to determine whether a store is to the target code area. All of these requirements eliminate the ability of the emulator to practice significant optimization of the code run on the host processor and make this type of emulation much slower than running the target application on a target processor. Emulation rates less than one-quarter as fast as state of the art processors are considered very good. In general, this has relegated this type of emulation software to uses where the capability of running applications designed for another processor is useful but not primary.

In Figure 1(d), a particular method of emulating a target application program on a host processor which provides relatively good performance for a very limited series of target applications is illustrated. The target application furnishes instructions to an emulator which changes those instructions into instructions for the host processor and the host operating system. The host processor is a Digital Equipment Corporation Alpha RISC processor, and the host operating system is Microsoft NT. The only target applications which may be run by this system are 32 bit applications designed to be executed by a target X86 processor with a Windows WIN32s compliant

operating system. Since the host and target operating systems are almost identical, being designed to handle these same instructions, the emulator software may change the instructions very easily.

Moreover, the host operating system is already designed to respond to
5 the same calls that the target application generates so that the generation of virtual devices is considerably reduced.

Although this is technically an emulation system running a target application on a host processor, it is a very special case. Here the emulation software is running on a host operating system already
10 designed to run similar applications. This allows the calls from the target applications to be more simply directed to the correct facilities of the host and the host operating system. More importantly, this system will run only 32 bit Windows applications which probably amount to less than one percent of all X86 applications. Moreover,
15 this system will run applications on only one operating system, Windows NT; while X86 processors run applications designed for a large number of operating systems. Such a system, therefore, could be considered not to be compatible within the terms expressed earlier in this specification. Thus, a processor running such an emulator
20 cannot be considered to be a competitive X86 processor.

Another method of emulation by which software may be used to run portions of applications written for a first instruction set on a computer which recognizes a different instruction set is illustrated in Figure 1(e). This form of emulation software is typically utilized by a
25 programmer who may be porting an application from one computer system to another. Typically, the target application is being designed for some target computer other than the host machine on which the

emulator is being run. The emulator software analyzes the target instructions, translates those instructions into instructions which may be run on the host machine, and caches those host instructions so that they may be reused. This dynamic translation and caching
5 allows portions of applications to be run very rapidly. This form of emulator is normally used with software tracing tools to provide detailed information about the behavior of a target program being run. The output of a tracing tool may, in turn, be used to drive an analyzer program which analyzes the trace information.

10 In order to determine how the code actually functions, an emulator of this type, among other things, runs with the host operating system on the host machine, furnishes the virtual hardware which the host operating system does not provide, and otherwise maps the operations of the computer for which the application was designed to the
15 hardware resources of the host machine in order to carry out the operations of the program being run. This software virtualizing of hardware and mapping to the host computer can be very slow and incomplete.

Moreover, because it often requires a plurality of host instructions to
20 carry out one of the target instructions, exceptions including faults and traps which require a target operating system exception handler may be generated and cause the host to cease processing the host instructions at a point unrelated to target instruction boundaries. When this happens, it may be impossible to handle the exception
25 correctly because the state of the host processor and memory is incorrect. If this is the case, the emulator must be stopped and rerun to trace the operations which generated the exception. Thus, even

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though such an emulator may run sequences of target code very rapidly, it has no method for recovering from these exceptions so cannot run any significant portion of an application rapidly.

This is not a particular problem with this form of emulator because
5 the functions being performed by the emulators, tracers, and the associated analyzers are directed to generating new programs or porting old programs to another machine so that the speed at which the emulator software runs is rarely at issue. That is, a programmer is usually not interested in how fast the code produced by a emulator
10 runs on the host machine but in whether the emulator produces code which is executable on the machine for which it is designed and which will run rapidly on that machine. Consequently, this type of emulation software does not provide a method for running application programs written in a first instruction set to run on a different type of
15 microprocessor for other than programming purposes. An example of this type of emulation software is described in an article entitled, "Shade: A Fast Instruction-Set Simulator for Execution Profiling," Cmelik and Keppel.

It is desirable to provide competitive microprocessors which are faster
20 and less expensive than state of the art microprocessors yet are entirely compatible with target application programs designed for state of the art microprocessors running any operating systems available for those microprocessors.

More particularly, it is desirable to provide a host processor having
25 circuitry for enhancing the speed of operation and compatibility of such a processor.

Summary Of The Invention

It is, therefore, an object of the present invention to provide a host processor with apparatus for enhancing the operation of a microprocessor which is less expensive than conventional state of the art microprocessors yet is compatible with and capable of running application programs and operating systems designed for other microprocessors at a faster rate than those other microprocessors.

This and other objects of the present invention are realized by a memory controller for a microprocessor including apparatus to both detect a failure of speculation on the nature of the memory being addressed, and apparatus to recover from such failures.

These and other objects and features of the invention will be better understood by reference to the detailed description which follows taken together with the drawings in which like elements are referred to by like designations throughout the several views.

Brief Description Of The Drawings

Figures 1(a)-(e) are diagrams illustrating the manner of operation of microprocessors designed in accordance with the prior art.

Figure 2 is a block diagram of a microprocessor designed in accordance with the present invention running an application designed for a different microprocessor.

Figure 3 is a diagram illustrating a portion of the microprocessor shown in Figure 2.

Figure 4 is a block diagram illustrating a register file used in a microprocessor designed in accordance with the present invention.

Figure 5 is a block diagram illustrating a gated store buffer designed in accordance with the present invention.

- 5 Figure 6(a)-(c) illustrate instructions used in various microprocessors of the prior art and in a microprocessor designed in accordance with the present invention.

Figure 7 illustrates a method practiced by a software portion of a microprocessor designed in accordance with the present invention.

- 10 Figure 8 illustrates another method practiced by a software portion of a microprocessor designed in accordance with the present invention.

Figure 9 is a block diagram illustrating an improved computer system including the present invention.

- 15 Figure 10 is a block diagram illustrating a portion of the microprocessor shown in Figure 3.

Figure 11 is a block diagram illustrating in more detail a translation look aside buffer shown in the microprocessor of Figure 3.

Notation And Nomenclature

- 20 Some portions of the detailed descriptions which follow are presented in terms of symbolic representations of operations on data bits within a computer memory. These descriptions and representations are the means used by those skilled in the data processing arts to most effectively convey the substance of their work to others skilled in the

art. The operations are those requiring physical manipulations of physical quantities. Usually, though not necessarily, these quantities take the form of electrical or magnetic signals capable of being stored, transferred, combined, compared, and otherwise manipulated. It has
5 proven convenient at times, principally for reasons of common usage, to refer to these signals as bits, values, elements, symbols, characters, terms, numbers, or the like. It should be borne in mind, however, that all of these and similar terms are to be associated with the appropriate physical quantities and are merely convenient labels
10 applied to these quantities.

Further, the manipulations performed are often referred to in terms, such as adding or comparing, which are commonly associated with mental operations performed by a human operator. No such capability of a human operator is necessary or desirable in most cases
15 in any of the operations described herein which form part of the present invention; the operations are machine operations. Useful machines for performing the operations of the present invention include general purpose digital computers or other similar devices. In all cases the distinction between the method operations in operating a
20 computer and the method of computation itself should be borne in mind. The present invention relates to a method and apparatus for operating a computer in processing electrical or other (e.g. mechanical, chemical) physical signals to generate other desired physical signals.

25 During the following description, in some cases the target program is referred to as a program which is designed to be executed on an X86 microprocessor in order to provide exemplary details of operation

because the majority of emulators run X86 applications. However, the target program may be one designed to run on any family of target computers. This includes target virtual computers, such as Pcode machines, Postscript machines, or Java virtual machines.

5 Detailed Description

The present invention helps overcome the problems of the prior art and provides a microprocessor which is faster than microprocessors of the prior art, is capable of running all of the software for all of the operating systems which may be run by a large number of families of prior art microprocessors, yet is less expensive than prior art microprocessors.

Rather than using a microprocessor with more complicated hardware to accelerate its operation, the present invention is a part of a combination including an enhanced hardware processing portion (referred to as a "morph host" in this specification) which is much simpler than state of the art microprocessors and an emulating software portion (referred to as "code morphing software" in this specification) in a manner that the two portions function together as a microprocessor with more capabilities than any known competitive microprocessor. More particularly, a morph host is a processor which includes hardware enhancements to assist in having state of a target computer immediately at hand when an exception or error occurs, while code morphing software is software which translates the instructions of a target program to morph host instructions for the morph host and responds to exceptions and errors by replacing working state with correct target state when necessary so that correct

retranslations occur. Code morphing software may also include various processes for enhancing the speed of processing. Rather than providing hardware to enhance the speed of processing as do all of the very fast prior art microprocessors, the improved microprocessor
5 allows a large number of acceleration enhancement techniques to be carried out in selectable stages by the code morphing software.

Providing the speed enhancement techniques in the code morphing software allows the morph host to be implemented using much less complicated hardware which is faster and substantially less expensive
10 than the hardware of prior art microprocessors. As a comparison, one embodiment including the present invention designed to run all available X86 applications is implemented by a morph host including approximately one-quarter of the number of gates of the Pentium Pro microprocessor yet runs X86 applications substantially faster than
15 does the Pentium Pro microprocessor or any other known microprocessor capable of processing these applications.

The code morphing software utilizes certain techniques which have previously been used only by programmers designing new software or emulating new hardware. The morph host includes hardware
20 enhancements especially adapted to allow the acceleration techniques - provided by the code morphing software to be utilized efficiently. These hardware enhancements allow the code morphing software to implement acceleration techniques over a broader range of instructions. These hardware enhancements also permit additional
25 acceleration techniques to be practiced by the code morphing software which are unavailable in hardware processors and could not be implemented in those processors except at exorbitant cost. These

techniques significantly increase the speed of the microprocessor which includes the present invention compared to the speeds of prior art microprocessors practicing the execution of native instruction sets.

For example, the code morphing software combined with the
5 enhanced morph host allows the use of techniques which allow the reordering and rescheduling of primitive instructions generated by a sequence of target instructions without requiring the addition of significant circuitry. By allowing the reordering and rescheduling of a number of target instructions together, other optimization techniques
10 can be used to reduce the number of processor steps which are necessary to carry out a group of target instructions to fewer than those required by any other microprocessors which will run the target applications.

The code morphing software combined with the enhanced morph host
15 translates target instructions into instructions for the morph host on the fly and caches those host instructions in a memory data structure (referred to in this specification as a "translation buffer"). The use of a translation buffer to hold translated instructions allows instructions to be recalled without rerunning the lengthy process of determining
20 which primitive instructions are required to implement each target instruction, addressing each primitive instruction, fetching each primitive instruction, optimizing the sequence of primitive instructions, allocating assets to each primitive instruction, reordering the primitive instructions, and executing each step of each sequence
25 of primitive instructions involved each time each target instruction is executed. Once a target instruction has been translated, it may be

recalled from the translation buffer and executed without the need for any of these myriad of steps.

A primary problem of prior art emulation techniques has been the inability of these techniques to handle with good performance exceptions generated during the execution of a target program. This is especially true of exceptions generated in running the target application which are directed to the target operating system where the correct target state must be available at the time of any such exception for proper execution of the exception and the instructions which follow. Consequently, the emulator is forced to keep accurate track of the target state at all times and must constantly check to determine whether a store is to the target code area. Other exceptions create similar problems. For example, exceptions can be generated by the emulator to detect particular target operations which have been replaced by some particular host function. In particular, various hardware operations of a target processor may be replaced by software operations provided by the emulator software. Additionally, the host processor executing the host instructions derived from the target instructions can also generate exceptions. All of these exceptions can occur either during the attempt to change target instructions into host-instructions by the emulator, or when the host translations are executed on the host processor. An efficient emulation must provide some manner of recovering from these exceptions efficiently and in a manner that the exception may be correctly handled. None of the prior art does this for all software which might be emulated.

In order to overcome these limitations of the prior art, a number of hardware improvements are included in the enhanced morph host.

These improvements include a gated store buffer and a large plurality of additional processor registers. Some of the additional registers allow the use of register renaming to lessen the problem of instructions needing the same hardware resources. The additional registers also allow the maintenance of a set of host or working registers for processing the host instructions and a set of target registers to hold the official state of the target processor for which the target application was created. The target (or shadow) registers are connected to their working register equivalents through a dedicated interface that allows an operation called "commit" to quickly transfer the content of all working registers to official target registers and allows an operation called "rollback" to quickly transfer the content of all official target registers back to their working register equivalents. The gated store buffer stores working memory state changes on an "uncommitted" side of a hardware "gate" and official memory state changes on a "committed" side of the hardware gate where these committed stores "drain" to main memory. A commit operation transfers stores from the uncommitted side of the gate to the committed side of the gate. The additional official registers and the gated store buffer allow the state of memory and the state of the target registers to be updated together once one or a group of target instructions have been translated and run without error.

These updates are chosen by the code morphing software to occur on integral target instruction boundaries. Thus, if the primitive host instructions making up a translation of a series of target instructions are run by the host processor without generating exceptions, then the working memory stores and working register state generated by those

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instructions are transferred to official memory and to the official target registers. In this manner, if an exception occurs when processing the host instructions at a point which is not on the boundary of one or a set of target instructions being translated, the original state in the target registers at the last update (or commit) may be recalled to the working registers and uncommitted memory stores in the gated store buffer may be dumped. Then, for the case where the exception generated is a target exception, the target instructions causing the target exception may be retranslated one at a time and executed in serial sequence as they would be executed by a target microprocessor. As each target instruction is correctly executed without error, the state of the target registers may be updated; and the data in the store buffer gated to memory. Then, when the exception occurs again in running the host instructions, the correct state of the target computer is held by the target registers of the morph host and memory; and the operation may be correctly handled without delay. Each new translation generated by this corrective translating may be cached for future use as it is translated or alternatively dumped for a one time or rare occurrence such as a page fault. This allows the microprocessor created by the combination of the code morphing software and the morph host to execute the instructions more rapidly than processors for which the software was originally written.

It should be noted that in executing target programs using the microprocessor including the present invention, many different types of exceptions can occur which are handled in different manners. For example, some exceptions are caused by the target software generating an exception which utilizes a target operating system

exception handler. The use of such an exception handler requires that the code morphing software include routines for emulating the entire exception handling process including any hardware provided by the target computer for handling the process. This requires that the code morphing software provide for saving the state of the target processor so that it may proceed correctly after the exception has been handled. Some exceptions like a page fault, which requires fetching data in a new page of memory before the process being translated may be implemented, require a return to the beginning of the process being translated after the exception has been handled. Other exceptions implement a particular operation in software where that operation is not provided by the hardware. These require that the exception handler return the operation to the next step in the translation after the exception has been handled. Each of these different types of exceptions may be efficiently handled by the microprocessor including the present invention.

Additionally, some exceptions are generated by host hardware and detect a variety of host and target conditions. Some exceptions behave like exceptions on a conventional microprocessor, but others are used by the code morphing software to detect failure of various speculations. In these cases, the code morphing software, using the state saving and restoring mechanisms described above, causes the target state to be restored to its most recent official version and generates and saves a new translation (or re-uses a previously generated safe translation) which avoids the failed speculation. This translation is then executed.

The morph host includes additional hardware exception detection mechanisms that in conjunction with the rollback and retranslate method described above allow further optimization. Examples are a means to distinguish memory from memory mapped I/O and a means
5 to eliminate memory references by protecting addresses or address ranges thus allowing target variables to be kept in registers.

For the case where exceptions are used to detect failure of other speculations, such as whether an operation affects memory or memory mapped I/O, recovery is accomplished by the generation of
10 new translations with different memory operations and different optimizations.

Figure 2 is a diagram of morph host hardware designed in accordance with the present invention represented running the same application program which is being run on the CISC processor of Figure 1(a). As
15 may be seen, the microprocessor includes the code morphing software portion and the enhanced hardware morph host portion described above. The target application furnishes the target instructions to the code morphing software for translation into host instructions which the morph host is capable of executing. In the meantime, the target
20 operating system receives calls from the target application program and transfers these to the code morphing software. In a preferred embodiment of the microprocessor, the morph host is a very long instruction word (VLIW) processor which is designed with a plurality of processing channels. The overall operation of such a processor is
25 further illustrated in Figure 6(c).

In Figure 6(a)-(c) are illustrated instructions adapted for use with each of a CISC processor, a RISC processor, and a VLIW processor. As may be seen, the CISC instructions are of varied lengths and may include a plurality of more primitive operations (e.g., load and add). The RISC instructions, on the other hand, are of equal length and are essentially primitive operations. The single very long instruction for the VLIW processor illustrated includes each of the more primitive operations (i.e., load, store, integer add, compare, floating point multiply, and branch) of the CISC and RISC instructions. As may be seen in Figure 6(c), each of the primitive instructions which together make up a single very long instruction word is furnished in parallel with the other primitive instructions either to one of a plurality of separate processing channels of the VLIW processor or to memory to be dealt with in parallel by the processing channels and memory. The results of all of these parallel operations are transferred into a multiported register file.

A VLIW processor which may be the basis of the morph host is a much simpler processor than the other processors described above . It does not include circuitry to detect issue dependencies or to reorder, optimize, and reschedule primitive instructions. This, in turn, allows faster processing at higher clock rates than is possible with either the processors for which the target application programs were originally designed or other processors using emulation programs to run target application programs. However, the processor is not limited to VLIW processors and may function as well with any type of processor such as a RISC processor.

The code morphing software of the microprocessor shown in Figure 2 includes a translator portion which decodes the instructions of the target application, converts those target instructions to the primitive host instructions capable of execution by the morph host, optimizes
5 the operations required by the target instructions, reorders and schedules the primitive instructions into VLIW instructions (a translation) for the morph host, and executes the host VLIW instructions. The operations of the translator are illustrated in Figure 7 which illustrates the operation of the main loop of the code
10 morphing software.

In order to accelerate the operation of the microprocessor which includes the code morphing software and the enhanced morph host hardware, the code morphing software includes a translation buffer as is illustrated in Figure 2. The translation buffer of one embodiment is
15 a software data structure which may be stored in memory; a hardware cache might also be utilized in a particular embodiment. The translation buffer is used to store the host instructions which embody each completed translation of the target instructions. As may be seen, once the individual target instructions have been translated and the
20 resulting host instructions have been optimized, reordered, and rescheduled, the resulting host translation is stored in the translation buffer. The host instructions which make up the translation are then executed by the morph host. If the host instructions are executed without generating an exception, the translation may thereafter be
25 recalled whenever the operations required by the target instruction or instructions are required.

Thus, as shown in Figure 7, a typical operation of the code morphing software of the microprocessor when furnished the address of a target instruction by the application program is to first determine whether the target instruction at the target address has been translated. If the

5 target instruction has not been translated, it and subsequent target instructions are fetched, decoded, translated, and then (possibly) optimized, reordered, and rescheduled into a new host translation, and stored in the translation buffer by the translator. As will be seen later, there are various degrees of optimization which are possible.

10 The term "optimization" is often used generically in this specification to refer to those techniques by which processing is accelerated. For example, reordering is one form of optimization which allows faster processing and which is included within the term. Many of the optimizations which are possible have been described within the prior

15 art of compiler optimizations, and some optimizations which were difficult to perform within the prior art like "super-blocks" come from VLIW research. Control is then transferred to the translation to cause execution by the enhanced morph host hardware to resume.

When the particular target instruction sequence is next encountered

20 in running the application, the host translation will then be found in the translation buffer and immediately executed without the necessity of translating, optimizing, reordering, or rescheduling. Using the advanced techniques described below, it has been estimated that the translation for a target instruction (once completely translated) will be

25 found in the translation buffer all but once for each one million or so executions of the translation. Consequently, after a first translation, all of the steps required for translation such as decoding, fetching

primitive instructions, optimizing the primitive instructions, rescheduling into a host translation, and storing in the translation buffer may be eliminated from the processing required. Since the processor for which the target instructions were written must decode,
5 fetch, reorder, and reschedule each instruction each time the instruction is executed, this drastically reduces the work required for executing the target instructions and increases the speed of the microprocessor of the improved processor.

In eliminating all of these steps required in execution of a target
10 application by prior art processors, the microprocessor including the present invention overcomes problems of the prior art which made such operations impossible at any reasonable speed. For example, some of the techniques of the improved microprocessor were used in the emulators described above used for porting applications to other
15 systems. However, some of these emulators had no way of running more than short portions of applications because in processing translated instructions, exceptions which generate calls to various system exception handlers were generated at points in the operation at which the state of the host processor had no relation to the state of
20 a target processor processing the same instructions. Because of this, the state of the target processor at the point at which such an exception was generated was not known. Thus, correct state of the target machine could not be determined; and the operation would have to be stopped, restarted, and the correct state ascertained before
25 the exception could be serviced and execution continued. This made running an application program at host speed impossible.

The morph host hardware of the present invention includes a number of enhancements which overcome this problem. These enhancements are each illustrated in Figures 3, 4, and 5. In order to determine the correct state of the registers at the time an error occurs, a set of

5 official target registers is provided by the enhanced hardware to hold the state of the registers of the target processor for which the original application was designed. These target registers may be included in each of the floating point units, any integer units, and any other execution units. These official registers have been added to the morph

10 host of the present invention along with an increased number of normal working registers so that a number of optimizations including register renaming may be practiced. One embodiment of the enhanced hardware includes sixty-four working registers in the integer unit and thirty-two working registers in the floating point unit.

15 The embodiment also includes an enhanced set of target registers which include all of the frequently changed registers of the target processor necessary to provide the state of that processor ; these include condition control registers and other registers necessary for control of the simulated system.

20 It should be noted that depending on the type of enhanced processing hardware utilized by the morph host, a translated instruction sequence may include primitive operations which constitute a plurality of target instructions from the original application. For example, a VLIW microprocessor may be capable of running a

25 plurality of either CISC or RISC instructions at once as is illustrated in Figure 6(a)-(c). Whatever the morph host type, the state of the target registers of the morph host hardware of the invention is not

changed except at an integral target instruction boundary; and then all target registers are updated. Thus, if the microprocessor of the present invention is executing a target instruction or instructions which have been translated into a series of primitive instructions

5 which may have been reordered and rescheduled into a host translation, when the processor begins executing the translated instruction sequence, the official target registers hold the values which would be held by the registers of the target processor for which the application was designed when the first target instruction was

10 addressed. After the morph host has begun executing the translated instructions, however, the working registers hold values determined by the primitive operations of the translated instructions executed to that point. Thus, while some of these working registers may hold values which are identical to those in the official target registers,

15 others of the working registers hold values which are meaningless to the target processor. This is especially true in an embodiment which provides many more registers than does a particular target machine in order to allow advanced acceleration techniques. Once the translated host instructions begin, the values in the working registers are

20 whatever those translated host instructions determine the condition of those registers to be. If a set of translated host instructions is executed without generating an exception, then the new working register values determined at the end of the set of instructions are transferred together to the official target registers (possibly including a

25 target instruction pointer register). In the present embodiment of the processor, this transfer occurs outside of the execution of the host

instructions in an additional pipeline stage so it does not slow operation of the morph host.

In a similar manner, a gated store buffer such as that illustrated in Figure 5 is utilized in the hardware of the improved microprocessor to control the transfer of data to memory. The gated store buffer includes a number of elements each of which may hold the address and data for a memory store operation. These elements may be implemented by any of a number of different hardware arrangements (e.g., first-in first-out buffers); the embodiment illustrated is implemented utilizing random access memory and three dedicated working registers. The three registers store, respectively, a pointer to the head of the queue of memory stores, a pointer to the gate, and a pointer to the tail of the queue of the memory stores. Memory stores positioned between the head of the queue and the gate are already committed to memory, while those positioned between the gate of the queue and the tail are not yet committed to memory. Memory stores generated during execution of host translations are placed in the store buffer by the integer unit in the order generated during the execution of the host instructions by the morph host but are not allowed to be written to memory until a commit operation is encountered in a host instruction. Thus, as translations execute, the store operations are placed in the queue. Assuming these are the first stores so that no other stores are in the gated store buffer, both the head and gate pointers will point to the same position. As each store is executed, it is placed in the next position in the queue and the tail point is incremented to the next position (upward in the figure). This continues until a commit command is executed. This will normally

happen when the translation of a set of target instructions has been completed without generating an exception or a error exit condition. When a translation has been executed by the morph host without error, then the memory stores in the store buffer generated during
5 execution are moved together past the gate of the store buffer (committed) and subsequently written to memory. In the embodiment illustrated, this is accomplished by copying the value in the register holding the tail pointer to the register holding the gate pointer.

Thus, it may be seen that both the transfer of register state from
10 working registers to official target registers and the transfer of working memory stores to official memory occur together and only on boundaries between integral target instructions in response to explicit commit operations.

This allows the microprocessor to recover from target exceptions
15 which occur during execution by the enhanced morph host without any significant delay. If a target exception is generated during the running of any translated instruction or instructions, that exception is detected by the morph host hardware or software. In response to the detection of the target exception, the code morphing software may
20 cause the values retained in the official registers to be placed back into the working registers and any non-committed memory stores in the gated store buffer to be dumped (an operation referred to as "rollback"). The memory stores in the gated store buffer of Figure 5 may be dumped by copying the value in the register holding the gate
25 pointer to the register holding the tail pointer.

Placing the values from the target registers into the working registers may place the address of the first of the target instructions which were running when the exception occurred in the working instruction pointer register. Beginning with this official state of the target processor in the working registers, the target instructions which were running when the exception occurred are retranslated in serial order without any reordering or other optimizing. After each target instruction is newly decoded and translated into a new host translation, the translated host instruction representing the target instructions is executed by the morph host and causes or does not cause an exception to occur. (If the morph host is other than a VLIW processor, then each of the primitive operations of the host translation is executed in sequence. If no exception occurs as the host translation is run, the next primitive function is run.) This continues until an exception re-occurs or the single target instruction has been translated and executed. In one embodiment, if a translation of a target instruction is executed without an exception being generated, then the state of working registers is transferred to the target registers and any data in the gated store buffer is committed so that it may be transferred to memory. However, if an exception re-occurs during the running of a translation, then the state of the target registers and memory has not changed but is identical to the state produced in a target computer when the exception occurs. Consequently, when the target exception is generated, the exception will be correctly handled by the target operating system.

Similarly, once a first target instruction of the series of instructions the translation of which generated an exception has been executed

without generating an exception, the target instruction pointer points to the next of the target instructions. This second target instruction is decoded and retranslated without optimizing or reordering in the same manner as the first. As each of the host translations of a single target instruction is processed by the morph host, any exception generated will occur when the state of the target registers and memory is identical to the state which would occur in the target computer. Consequently, the exception may be immediately and correctly handled. These new translations may be stored in the translation buffer as the correct translations for that sequence of instructions in the target application and recalled whenever the instructions are rerun.

Other embodiments of the invention for accomplishing the same result as the gated store buffer of Figure 5 might include arrangements for transferring stores directly to memory while recording data sufficient to recover state of the target computer in case the execution of a translation results in an exception or an error necessitating rollback. In such a case, the effect of any memory stores which occurred during translation and execution would have to be reversed and the memory state existing at the beginning of the translation restored; while working registers would have to receive data held in the official target registers in the manner discussed above. One embodiment for accomplishing this maintains a separate target memory to hold the original memory state which is then utilized to replace overwritten memory if a rollback occurs. Another embodiment for accomplishing memory rollback logs each store and the memory data replaced as they occur, and then reverses the store process if rollback is required.

The code morphing software of the present invention provides an additional operation which greatly enhances the speed of processing programs which are being translated. In addition to simply translating the instructions, optimizing, reordering, rescheduling, caching, and executing each translation so that it may be rerun
5 whenever that set of instructions needs to be executed, the translator also links the different translations to eliminate in almost all cases a return to the main loop of the translation process. Figure 8 illustrates the steps carried out by the translator portion of the code morphing software in accomplishing this linking process. It will be understood
10 by those skilled in the art that this linking operation essentially eliminates the return to the main loop for most translations of instructions, which eliminates this overhead.

Presume for exemplary purposes that the target program being run
15 consists of X86 instructions. When a translation of a sequence of target instructions occurs and the primitive host instructions are reordered and rescheduled, two primitive instructions may occur at the end of each host translation. The first is a primitive instruction which updates the value of the instruction pointer for the target
20 processor (or its equivalent); this instruction is used to place the correct address of the next target instruction in the target instruction pointer register. Following this primitive instruction is a branch instruction which contains the address of each of two possible targets for the branch. The manner in which the primitive instruction which
25 precedes the branch instruction may update the value of the instruction pointer for the target processor is to test the condition code for the branch in the condition code registers and then determine

whether one of the two branch addresses indicated by the condition controlling the branch is stored in the translation buffer. The first time the sequence of target instructions is translated, the two branch targets of the host instruction both hold the same host processor address for the main loop of the translator software.

When the host translation is completed, stored in the translation buffer, and executed for the first time, the instruction pointer is updated in the target instruction pointer register (as are the rest of the target registers); and the operation branches back to the main loop.

At the main loop, the translator software looks up the instruction pointer to the next target instruction in the target instruction pointer register. Then the next target instruction sequence is addressed.

Presuming that this sequence of target instructions has not yet been translated and therefore a translation does not reside in the

translation buffer, the next set of target instructions is fetched from memory, decoded, translated, optimized, reordered, rescheduled, cached in the translation buffer, and executed. Since the second set of target instructions follows the first set of target instructions, the primitive branch instruction at the end of the host translation of the first set of target instructions is automatically updated to substitute the address of the host translation of the second set of target instructions as the branch address for the particular condition controlling the branch.

If then, the second translated host instruction were to loop back to the first translated host instruction, the branch operation at the end of the second translation would include the main loop address and the X86 address of the first translation as the two possible targets for the

branch. The update-instruction-pointer primitive operation preceding the branch tests the condition and determines that the loop back to the first translation is to be taken and updates the target instruction pointer to the X86 address of the first translation. This causes the
5 translator to look in the translation buffer to see if the X86 address being sought appears there. The address of the first translation is found, and its value in host memory space is substituted for the X86 address in the branch at the end of the second host translated instruction. Then, the second host translated instruction is cached
10 and executed. This causes the loop to be run until the condition causing the branch from the first translation to the second translation fails, and the branch takes the path back to the main loop. When this happens, the first translated host instruction branches back to the main loop where the next set of target instructions designated by the
15 target instruction pointer is searched for in the translation buffer, the host translation is fetched from the cache; or the search in the translation buffer fails, and the target instructions are fetched from memory and translated. When this translated host instruction is cached in the translation buffer, its address replaces the main loop
20 address in the branch instruction which ended the loop.

In this manner, the various translated host instructions are chained to one another so that the need to follow the long path through the translator main loop only occurs where a link does not exist. Eventually, the main loop references in the branch instructions of
25 host instructions are almost completely eliminated. When this condition is reached, the time required to fetch target instructions, decode target instructions, fetch the primitive instructions which

make up the target instructions, optimize those primitive operations, reorder the primitive operations, and reschedule those primitive operations before running any host instruction is eliminated. Thus, in contrast to all prior art microprocessors which must take each of these steps each time any application instruction sequence is run, the work required to run any set of target instructions using the improved microprocessor after the first translation has taken place is drastically reduced. This work is further reduced as each set of translated host instructions is linked to the other sets of translated host instructions. In fact, it is estimated that translation will be needed in less than one translation execution out of one million during the running of an application.

Those skilled in the art will recognize that the implementation of the microprocessor requires a large translation buffer since each set of instructions which is translated is cached in order that it need not be translated again. Translators designed to function with applications programmed for different systems will vary in their need for supporting buffer memory. However, one embodiment of the microprocessor designed to run X86 programs utilizes a translation buffer of two megabytes of random access memory.

Two additional hardware enhancements help to increase the speed at which applications can be processed by the microprocessor which includes the present invention. The first of these is an abnormal/normal (A/N) protection bit stored with each address translation in a translation look-aside buffer (TLB) (see Figure 3) where lookup of the physical address of target instructions is first accomplished. Target memory operations within translations can be

of two types, ones which operate on memory (normal) or ones which operate on a memory mapped I/O device (abnormal).

A normal access which affects memory completes normally. When instructions operate on memory, the optimizing and reordering of those instructions is appropriate and greatly aids in speeding the operation of any system using the microprocessor which includes the present invention. On the other hand, the operations of an abnormal access which affects an I/O device often must be practiced in the precise order in which those operations are programmed without the elimination of any steps or they may have some adverse affect at the I/O device. For example, a particular I/O operation may have the effect of clearing an I/O register; if the primitive operations take place out of order, then the result of the operations may be different than the operation commanded by the target instruction. Without a means to distinguish memory from memory mapped I/O, it is necessary to treat all memory with the conservative assumptions used to translate instruction which affect memory mapped I/O. This severely restricts the nature of optimizations that are achievable. Because prior art emulators lacked means to both detect a failure of speculation on the nature of the memory being addressed, and means to recover from such failures, their performance was restricted.

In one embodiment of the microprocessor illustrated in Figure 11, the A/N bit is a bit which may be set in the translation look-aside buffer to indicate either a memory page or memory-mapped I/O. The translation look-aside buffer stores page table entries for memory accesses. Each such entry includes a virtual address being accessed and the physical address at which the data sought may be accessed

as well as other information regarding the entry. In the present invention, the A/N bit is part of that other information and indicates whether the physical address is a memory address or a memory-mapped I/O address. A translation of an operation which affects
5 memory as though it were a memory operation is actually a speculation that the operation is one affecting memory. In one embodiment, when the code morphing software first attempts to execute a translation which requires an access of either memory or a memory-mapped I/O device, it is actually presuming that the access
10 is a memory access. In a different embodiment, the software might presume the target command requires an I/O access. Presuming an access of that address has not previously been accomplished, there will be no entry in the translation look-aside buffer; and the access will fail in the translation look-aside buffer. This failure causes the
15 software to do a page table lookup and fill a storage location of the translation look-aside buffer with the page table entry to provide the correct physical address translation for the virtual address. In accomplishing this, the software causes the A/N bit for the physical address to be entered in the translation look-aside buffer. Then
20 another attempt to execute the access takes place once more assuming that the access is of a memory address. As the access is attempted, the target memory reference is checked by comparing the access type presumed (normal or abnormal) against the A/N protection bit now in the TLB page table entry. When the access type
25 does not match the A/N protection, an exception occurs. If the operation in fact affects memory, then the optimizing, reordering, and rescheduling techniques described above were correctly applied during translation. If the comparison with the A/N bit in the TLB shows that

the operation, however, affects an I/O device, then execution causes an exception to be taken; and the translator produces a new translation one target instruction at a time without optimizing, reordering, or rescheduling of any sort. Similarly, if a translation
5 incorrectly assumes an I/O operation for an operation which actually affects memory, execution causes an exception to be taken; and the target instructions are retranslated using the optimizing, reordering, and rescheduling techniques. In this manner, the processor can enhance performance beyond what has been traditionally possible.

10 It will be recognized by those skilled in the art that the technique which uses the A/N bit to determine whether a failure of speculation has occurred as to whether an access is to memory or a memory-mapped I/O device may also be used for speculations regarding other properties of memory-mapped addresses. For example, different types
15 of memory might be distinguished using such a normal/abnormal bit. Other similar uses is distinguishing memory properties will be found by those skilled in the art.

One of the most frequent speculations practiced by the improved microprocessor is that target exceptions will not occur within a
20 translation. This allows significant optimization over the prior art. First, target state does not have to be updated on each target instruction boundary, but only on target instruction boundaries which occur on translation boundaries. This eliminates instructions necessary to save target state on each target instruction boundary.
25 Optimizations that would previously have been impossible in scheduling and removing redundant operations are also made possible.

The improved microprocessor is admirably adapted to select the appropriate process of translation. In accordance with the method of translating described above, a set of instructions may first be translated as though it were to affect memory. When the optimized, reordered, and rescheduled host instructions are then executed, the address may be found to refer to an I/O device by the condition of the A/N bit provided in the translation look-aside buffer. The comparison of the A/N bit and the translated instruction address which shows that an operation is an I/O operation generates an error exception which causes a software initiated rollback procedure to occur, causing any uncommitted memory stores to be dumped and the values in the target registers to be placed back into the working registers. Then the translation starts over, one target instruction at a time without optimization, reordering, or rescheduling. This re-translation is the appropriate host translation for an I/O device.

In a similar manner, it is possible for a memory operation to be incorrectly translated as an I/O operation. The error generated may be used to cause its correct re-translation where it may be optimized, reordered, and rescheduled to provide faster operation.

Prior art emulators have also struggled with what is generally referred to as self modifying code. Should a target program write to the memory that contains target instructions, this will cause translations that exist for these target instructions to become "stale" and no longer valid. It is necessary to detect these stores as they occur dynamically. In the prior art, such detection has to be accomplished with extra instructions for each store. This problem is larger in scope than programs modifying themselves. Any agent which can write to

memory, such as a second processor or a DMA device, can also cause this problem.

The present invention deals with this problem by another enhancement to the morph host. A translation bit (T bit) which may also be stored in the translation look-aside buffer is used to indicate target memory pages for which translations exist. The T bit thus possibly indicates that particular pages of target memory contain target instructions for which host translations exist which would become stale if those target instructions were to be overwritten. If an attempt is made to write to the protected pages in memory, the presence of the translation bit will cause an exception which when handled by the code morphing software can cause the appropriate translation(s) to be invalidated or removed from the translation buffer. The T bit can also be used to mark other target pages that translation may rely upon not being written.

This may be understood by referring to Figure 3 which illustrates in block diagram form the general functional elements of the microprocessor which includes the invention. When the morph host executes a target program, it actually runs the translator portion of the code morphing software which includes the only original untranslated host instructions which effectively run on the morph host. To the right in the figure is illustrated memory divided into a host portion including essentially the translator and the translation buffer and a target portion including the target instructions and data, including the target operating system. The morph host hardware begins executing the translator by fetching host instructions from memory and placing those instructions in an instruction cache. The

translator instructions generate a fetch of the first target instructions stored in the target portion of memory. Carrying out a target fetch causes the integer unit to look to the official target instruction pointer register for a first address of a target instruction. The first address is then accessed in the translation look-aside buffer of the memory management unit. The memory management unit includes hardware for paging and provides memory mapping facilities for the TLB. Presuming that the TLB is correctly mapped so that it holds lookup data for the correct page of target memory, the target instruction pointer value is translated to the physical address of the target instruction. At this point, the condition of the bit (T bit) indicating whether a translation has been accomplished for the target instruction is detected; but the access is a read operation, and no T bit exception will occur. The condition of the A/N bit indicating whether the access is to memory or memory mapped I/O is also detected. Presuming the last mentioned bit indicates a memory location, the target instruction is accessed in target memory since no translation exists. The target instruction and subsequent target instructions are transferred as data to the morph host computing units and translated under control of the translator instructions stored in the instruction cache. The translator instructions utilize reordering, optimizing, and rescheduling techniques as though the target instruction affected memory. The resulting translation containing a sequence of host instructions is then stored in the translation buffer in host memory. The translation is transferred directly to the translation buffer in host memory via the gated store buffer. Once the translation has been stored in host memory, the translator branches to the translation which then executes. The

execution (and subsequent executions) will determine if the translation has made correct assumptions concerning exceptions and memory. Prior to executing the translation, the T bit for the target page(s) containing the target instructions that have been translated is set. This indication warns that the instruction has been translated; and, if an attempt to write to the target address occurs, the attempt generates an exception which causes the translation to possibly be invalidated or removed.

An additional hardware enhancement to the morph host is a circuit utilized to allow data which is normally stored in memory but is used quite often in the execution of an operation to be replicated (or "aliased") in an execution unit register in order to eliminate the time required to fetch the data from memory on each use. To accomplish this in one embodiment, the morph host is designed to respond to a "load and protect" command which copies the memory data to a working register 111 in an execution unit 110 shown in Figure 10 and places the memory address in a register 112 in that unit. Associated with the address register is a comparator 113. The comparator receives the addresses of loads and stores to the gated store buffer directed to memory during translations. If a memory address for either a load or a store compares with an address in the register 112 (or additional registers depending on the implementation), an exception is generated. The code morphing software responds to the exception by assuring that the memory address and the register hold the same correct data. In one embodiment, this is accomplished by rolling back the translation and reexecuting it without any "aliased" data in an execution register. Other possible methods of correcting

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the problem are to update the register with the latest memory data or memory with the latest load data.

It will be recognized by those skilled in the art that the microprocessor of the present invention may be connected in circuit with typical
5 computer elements to form a computer such as that illustrated in Figure 9. As may be seen, when used in a modern X86 computer the microprocessor is joined by a processor bus to memory and bus control circuitry. The memory and bus control circuitry is arranged to provide access to main memory as well as to cache memory which
10 may be utilized with the microprocessor. The memory and bus control circuitry also provides access to a bus such as a PCI or other local bus through which I/O devices may be accessed. The particular computer system will depend upon the circuitry utilized with a typical microprocessor which the microprocessor including the present
15 invention replaces.

In order to illustrate the operation of the processor of the present invention and the manner in which acceleration of execution occurs, the translation of a small sample of X86 target code to host primitive instructions is presented at this point. The sample illustrates the
20 translation of X86 target instructions to morph host instructions including various exemplary steps of optimizing, reordering, and rescheduling by the microprocessor which includes the invention. By following the process illustrated, the substantial difference between the operations required to execute the original instructions using the
25 target processor and the operations required to execute the translation on the host processor will become apparent to those skilled in the art.

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The original instruction illustrated in C language source code describes a very brief loop operation. Essentially, while some variable "n" which is being decremented after each loop remains greater than "0", a value "c" is stored at an address indicated by a pointer "*s" which is being incremented after each loop.

Original C code

```

    while( (n--)>0) {
        *s++=c
    }

```

Win32 x86 instructions produced by a compiler compiling this C code.

```

15  mov    %ecx,[%ebp+0xc]          // load c from memory address into the
    %ecx
    mov    %eax,[%ebp+0x8]         // load s from memory address into the
    %eax
20  mov    [%eax],%ecx             // store c into memory address s held
    in %eax
    add    %eax,#4                 // increment s by 4.
    mov    [%ebp+0x8],%eax         // store (s + 4) back into memory
    mov    %eax,[%ebp+0x10]        // load n from memory address into the
25  %eax
    lea    %ecx,[%eax-1]           // decrement n and store the result in
    %ecx
    mov    [%ebp+0x10],%ecx        // store (n-1) into memory
    and    %eax,%eax              // test n to set the condition codes
30  jg     .-0x1b                  // branch to the top of this section if
    "n>0"

```

Notation: [...] indicates an address expression for a memory operand. In the example above, the address for a memory operand is formed from the contents of a register added to a hexadecimal constant indicated by the 0x prefix. Target registers are indicated with the % prefix, e.g. %ecx is the ecx register. The destination of an operation is to the left.

40 Target instruction key:
 jg = jump if greater
 mov = move
 lea = load effective address
 and = AND

In this first portion of the sample, each of the individual X86 assembly language instructions for carrying out the execution of the operation

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defined by the C language statement is listed by the assembly language mnemonic for the operation followed by the parameters involved in the particular primitive operation. An explanation of the operation is also provided in a comment for each instruction. Even though the order of execution may be varied by the target processor from that shown, each of these assembly language instructions must be executed each time the loop is executed in carrying out the target C language instructions. Thus, if the loop is executed one hundred times, each instruction shown above must be carried out one hundred times.

Shows each X86 instruction shown above followed by the host instructions necessary to implement the X86 instruction.

```

15  mov  %ecx, [%ebp+0xc]      // load c from memory address into ecx
    add  R0, Rebp, 0xc        ; form the memory address and put it in
    R0                        ;
    ld   Recx, [R0]           ; load c from memory address in R0 into
    Recx                      ;
20  mov  %eax, [%ebp+0x8]      // load s from memory address into %eax
    add  R2, Rebp, 0x8        ; form the memory address and put it in
    R2                        ;
25  ld   Reax, [R2]           ; load s from memory address in R2 into
    Reax                      ;

    mov  [%eax], %ecx         // store c into memory address s held in %eax
30  st   [Reax], Recx         ; store c into memory address s held in
    Reax                      ;

    add  %eax, #4             // increment s by 4
35  add  Reax, Reax, 4         ; increment S by 4

    mov  [%ebp+0x8], %eax     // store (s + 4) back into memory
    add  R5, Rebp, 0x8        ; form the memory address and put it in
    R5                        ;
40  st   [R5], Reax           ; store (s + 4) back into memory

    mov  %eax, [%ebp+0x10]    // load n from memory address into %eax

```

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```

add    R7,Rebp,0x10          ; form the memory address and put it in
R7
ld     Reax,[R7]             ; load n from memory address into the
5  Reax

lea    %ecx, [%eax-1]        // decrement n and store the result in
%ecx

10  sub    Recx,Reax,1        ; decrement n and store the result in
    Recx

mov    [%ebp+0x10], %ecx     // store (n - 1) into memory

15  add    R9,Rebp,0x10      ; form the memory address and put it in
    R9

st     [R9],Recx            ; store (n - 1) into memory

20  and    %eax, %eax        // test n to set the condition codes

andcc  R11,Reax,Reax        ; test n to set the condition
codes

25  jg     .-0x1b            // branch to the top of this section if
    "n>0"

jg     mainloop,mainloop    ; jump to the main loop

30  Host Instruction key:
    ld = load                add = ADD                st =store
    sub = subtract            jg = jump if condition codes indicate
    greater
    andcc = and set the condition codes

35

```

The next sample illustrates the same target primitive instructions
 which carry out the C language instructions. However, following each
 primitive target instruction are listed primitive host instructions
 required to accomplish the same operation in one particular
 40 embodiment of the microprocessor of the invention in which the
 morph host is a VLIW processor designed in the manner described
 herein. It should be noted that the host registers which are shadowed
 by official target registers are designated by an "R" followed by the X86

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register designation so that, for example, Reax is the working register associated with the EAX official target register.

Adds host instructions necessary to perform X86 address computation and upper and lower segment limit checks.

```

5      mov  %ecx, [%ebp+0xc]          // load c

      add   R0,Rebp,0xc              ; form logical address into R0
      chkl  R0,Rss_limit             ; Check the logical address against segment
10     lower limit
      chku  R0,R_FFFFFFFF           ; Check the logical address against segment
      upper limit
      add   R1,R0,Rss_base           ; add the segment base to form the
      linear address
15     ld    Recx, [R1]              ; load c from memory address in R1 into
      Recx

      mov  %eax, [%ebp+0x8]          // load s

20     add   R2,Rebp,0x8              ; form logical address into R0
      chkl  R2,Rss_limit             ; Check the logical address against segment
      lower limit
      chku  R2,R_FFFFFFFF           ; Check the logical address against segment
      upper limit
25     add   R3,R2,Rss_base           ; add the segment base to form the
      linear address
      ld    Reax, [R3]              ; load s from memory address in R3 into
      Ra

30     mov  [%eax], %ecx             // store c into [s]

      chku  Reax,Rds_limit           ; Check the logical address against segment
      upper limit
      add   R4,Reax,Rds_base         ; add the segment base to form the
35     linear address
      st    [R4], Recx              ; store c into memory address s

      add   %eax, #4                 // increment s by 4

40     addcc Reax, Reax, 4            ; increment s by 4

      mov  [%ebp+0x8], %eax          // store (s + 4) to memory

      add   R5,Rebp,0x8              ; form logical address into R5
45     chkl  R5,Rss_limit             ; Check the logical address against segment
      lower limit
      chku  R5,R_FFFFFFFF           ; Check the logical address against segment
      upper limit
      add   R6,R5,Rss_base           ; add the segment base to form the
50     linear address
      st    [R6], Reax              ; store (s + 4) to memory address in R6

```

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```

mov  %eax, [%ebp+0x10]      // load n

add  R7, Rebp, 0x10         ; form logical address into R7
5   chk1 R7, Rss_limit      ; Check the logical address against segment
    lower limit
    chku R7, R_FFFFFFFF     ; Check the logical address against segment
    upper limit
    add  R8, R7, Rss_base   ; add the segment base to form the
10  linear address
    ld   Reax, [R8]         ; load n from memory address in R8 into
    Reax

    lea  %ecx, [%eax-1]     // decrement n
15  sub  Recx, Reax, 1       ; decrement n
    mov  [%ebp+0x10], %ecx  // store (n - 1)

    add  R9, Rebp, 0x10     ; form logical address into R9
20  chk1 R9, Rss_limit      ; Check the logical address against segment
    lower limit
    chku R9, R_FFFFFFFF     ; Check the logical address against segment
    upper limit
    add  R10, R9, Rss_base  ; add the segment base to form the
25  linear address
    st   [R10], Recx        ; store n-1 in Recx into memory using
    address in R10

    and  %eax, %eax         // test n to set the condition codes
30  andcc R11, Reax, Reax   ; test n to set the condition
    codes

    jg   .-0x1b             // branch to the top of this section if
35  "n>0"

    jg   mainloop, mainloop ; jump to the main loop

Host Instruction key:
40  chk1 + check lower limit
    chku = check upper limit

```

The next sample illustrates for each of the primitive target instructions the addition of host primitive instructions by which addresses needed for the target operation may be generated by the code morphing software. It should be noted that host address generation instructions are only required in an embodiment of a

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microprocessor in which code morphing software is used for address generation rather than address generation hardware. In a target processor such as an X86 microprocessor these addresses are generated using address generation hardware. Whenever address generation occurs in such an embodiment of the invention, the calculation is accomplished; and host primitive instructions are also added to check the address values to determine that the calculated addresses are within the appropriate X86 segment limits.

10 **Adds instructions to maintain the target X86 instruction pointer "eip" and the commit instructions that use the special morph host hardware to update X86 state.**

```

mov  %ecx, [%ebp+0xc]                // load c

add  R0, Rebp, 0xc
15  chkl R0, Rss_limit
    chku R0, R_FFFFFFFF
    add  R1, R0, Rss_base
    ld   Recx, [R1]
    add  Reip, Reip, 3                ; add X86 instruction length to
20  eip in Reip
    commit                          ; commits working state to
    official state

mov  %eax, [%ebp+0x8]                // load s

25  add  R2, Rebp, 0x8
    chkl R2, Rss_limit
    chku R2, R_FFFFFFFF
    add  R3, R2, Rss_base
30  ld   Reax, [R3]
    add  Reip, Reip, 3                ; add X86 instruction length to
    eip in Reip
    commit                          ; commits working state to
    official state

35  mov  [%eax], %ecx                // store c into [s]

    chku Reax, Rds_limit
    add  R4, Reax, Rds_base
40  st   [R4], Recx
    add  Reip, Reip, 2                ; add X86 instruction length to
    eip in Reip
    commit                          ; commits working state to
    official state

45  add  %eax, #4                    // increment s by 4

```

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```

    addcc Reax,Reax,4
    add Reip,Reip,5           ; add X86 instruction length to
5    eip in Reip              ; commits working state to
    commit
    official state

    mov [%ebp+0x8], %eax      // store (s + 4)

10   add R5,Rebp,0x8
    chkl R5,Rss_limit
    chku R5,R_FFFFFFFF
    add R6,R5,Rss_base
    st [R6],Reax
15   add Reip,Reip,3           ; add X86 instruction length to
    eip in Reip              ; commits working state to
    commit
    official state

20   mov %eax, [%ebp+0x10]    // load n

    add R7,Rebp,0x10
    chkl R7,Rss_limit
    chku R7,R_FFFFFFFF
25   add R8,R7,Rss_base
    ld Reax, [R8]
    add Reip,Reip,3           ; add X86 instruction length to
    eip in Reip              ; commits working state to
    commit
30   official state

    lea %ecx, [%eax-1]       // decrement n

    sub Recx,Reax,1
35   add Reip,Reip,3           ; add X86 instruction length to
    eip in Reip              ; commits working state to
    commit
    official state

40   mov [%ebp+0x10], %ecx    // store (n - 1)

    add R9,Rebp,0x10
    chkl R9,Rss_limit
    chku R9,R_FFFFFFFF
45   add R10,R9,Rss_base
    st [R10],Recx
    add Reip,Reip,3           add X86 instruction length to
    eip in Reip              ; commits working state to
    commit
50   official state

    and %eax, %eax           // test n

    andcc R11,Reax,Reax

```

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```

add    Reip, Reip, 3
commit                                ; commits working state to
official state

5  jg    .-0x1b                        // branch "n>0"

add    Rseq, Reip, Length(jg)
ldc    Rtarg, EIP(target)
selcc  Reip, Rseq, Rtarg
10  commit                            ; commits working state to
official state
jg     mainloop, mainloop

Host Instruction key:
15  commit = copy the contents of the working registers to the
official target registers and send working stores to memory

```

This sample illustrates the addition of two steps to each set of
 primitive host instructions to update the official target registers after
 the execution of the host instructions necessary to carry out each
 primitive target instruction and to commit the uncommitted values in
 the gated store buffer to memory. As may be seen, in each case, the
 length of the target instruction is added to the value in the working
 instruction pointer register (Reip). Then a commit instruction is
 executed. In one embodiment, the commit instruction copies the
 current value of each working register which is shadowed into its
 associated official target register and moves a pointer value
 designating the position of the gate of the gated store buffer from
 immediately in front of the uncommitted stores to immediately behind
 those stores so that they will be placed in memory.

It will be appreciated that the list of instructions illustrated last above
 are all of the instructions necessary to form a host translation of the
 original target assembly language instructions. If the translation were
 to stop at this point, the number of primitive host instructions would

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be much larger than the number of target instructions (probably six times as many instructions), and the execution could take longer than execution on a target processor. However, at this point, no reordering, optimizing, or rescheduling has yet taken place.

- 5 If an instruction is to be run but once, it may be that the time required to accomplish further reordering and other optimization is greater than the time to execute the translation as it exists at this point. If so, one embodiment of the microprocessor ceases the translation at this point, stores the translation, then executes it to
- 10 determine whether exception or errors occur. In this embodiment, steps of reordering and other optimization only occur if it is determined that the particular translation will be run a number times or otherwise should be optimized. This may be accomplished, for example by placing host instructions in each translation which count
- 15 the number of times a translation is executed and generate an exception (or branch) when a certain value is reached. The exception (or branch) transfers the operation to the code morphing software which then implements some or all of the following optimizations and any additional optimizations determined useful for that translation. A
- 20 second method of determining translations being run a number of times and requiring optimization is to interrupt the execution of translations at some frequency or on some statistical basis and optimize any translation running at that time. This would ultimately provide that the instructions most often run would be optimized.
- 25 Another solution would be to optimize each of certain particular types of host instructions such as those which create loops or are otherwise likely to be run most often.

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Optimization

=====

Assumes 32 bit flat address space which allows the elimination of segment base additions and some limit checks.

5

Win32 uses Flat 32b segmentation

Record Assumptions:

10

Rss_base==0

Rss_limit==0

Rds_base==0

Rds_limit==FFFFFFF

SS and DS protection check

15

mov %ecx,[%ebp+0xc] // load c

add R0,Rebp,0xc

20 chku R0,R_FFFFFFFF

ld Recx,[R0]

add Reip,Reip,3

commit

25 **mov %eax,[%ebp+0x8] // load s**

add R2,Rebp,0x8

chku R2,R_FFFFFFFF

ld Reax,[R2]

30 add Reip,Reip,3

commit

mov [%eax],%ecx // store c into [s]

35 chku Reax,R_FFFFFFFF

st [Reax],Recx

add Reip,Reip,2

commit

40 **add %eax,#4 // increment s by 4**

addcc Reax,Reax,4

add Reip,Reip,5

commit

45

mov [%ebp+0x8],%eax // store (s + 4)

add R5,Rebp,0x8

chku R5,R_FFFFFFFF

50 st [R5],Reax

add Reip,Reip,3

commit

mov %eax,[%ebp+0x10] // load n

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```

    add    R7,Rebp,0x10
    chku   R7,R_FFFFFFFF
    ld     Reax,[R7]
5    add    Reip,Reip,3
    commit

    lea     %ecx,[%eax-1]                // decrement n

10    sub    Recx,Reax,1
    add     Reip,Reip,3
    commit

    mov     [%ebp+0x10],%ecx             // store (n - 1)

15    add     R9,Rebp,0x10
    chku    R9,R_FFFFFFFF
    st      [R9],Recx
    add     Reip,Reip,3
20    commit

    and     %eax,%eax                   // test n

    andcc   R11,Reax,Reax
25    add     Reip,Reip,3
    commit

    jg      -.0x1b                      // branch "n>0"

30    add     Rseq,Reip,Length(jg)
    ldc     Rtarg,EIP(target)
    selcc   Reip,Rseq,Rtarg
    commit
    jg      mainloop,mainloop

35

```

This sample illustrates a first stage of optimization which may be practiced utilizing the improved microprocessor. This stage of optimization, like many of the other operations of the code morphing software, assumes an optimistic result. The particular optimization

40 assumes that a target application program which has begun as a 32 bit program written for a flat memory model provided by the X86 family of processors will continue as such a program. It will be noted that such an assumption is particular to the X86 family and would

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not necessarily be assumed with other families of processors being emulated.

If this assumption is made, then in X86 applications all segments are mapped to the same address space. This allows those primitive host instructions required by the X86 segmentation process to be eliminated. As may be seen, the segment values are first set to zero. Then, the base for data is set to zero, and the limit set to the maximum available memory. Then, in each set of primitive host instructions for executing a target primitive instruction, the check for a segment base value and the computation of the segment base address required by segmentation are both eliminated. This reduces the loop to be executed by two host primitive instructions for each target primitive instruction requiring an addressing function. At this point, the host instruction check for the upper memory limit still exists.

It should be noted that this optimization requires the speculation noted that the application utilizes a 32 bit flat memory model. If this is not true, then the error will be discovered as the main loop resolves the destination of control transfers and detects that the source assumptions do not match the destination assumptions. A new translation will then be necessary. This technique is very general and can be applied to a variety of segmentation and other "moded" cases where the "mode" changes infrequently, like debug, system management mode, or "real" mode.

Assume data addressed includes no bytes outside of computer memory limits which can only occur on unaligned page crossing memory references at the upper memory limit, and can be handled by special case software or hardware.

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```

    mov    %ecx, [%ebp+0xc]           // load c

    add    R0, Rebp, 0xc
    ld     Recx, [R0]
5    add    Reip, Reip, 3
    commit

    mov    %eax, [%ebp+0x8]           // load s

10   add    R2, Rebp, 0x8
    ld     Reax, [R2]
    add    Reip, Reip, 3
    commit

15   mov    [%eax], %ecx               // store c into [s]

    st     [Reax], Recx
    add    Reip, Reip, 2
    commit
20
    add    %eax, #4                   // increment s by 4

    addcc   Reax, Reax, 4
    add    Reip, Reip, 5
25   commit

    mov    [%ebp+0x8], %eax           // store (s + 4)

    add    R5, Rebp, 0x8
30   st     [R5], Reax
    add    Reip, Reip, 3
    commit

    mov    %eax, [%ebp+0x10]          // load n

35   add    R7, Rebp, 0x10
    ld     Reax, [R7]
    add    Reip, Reip, 3
    commit
40
    lea    %ecx, [%eax-1]             // decrement n

    sub    Recx, Reax, 1
    add    Reip, Reip, 3
45   commit

    mov    [%ebp+0x10], %ecx          // store (n - 1)

    add    R9, Rebp, 0x10
50   st     [R9], Recx
    add    Reip, Reip, 3
    commit

```

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```

and  %eax, %eax                // test n

andcc R11, Reax, Reax
add   Reip, Reip, 3
5    commit

jg   -.0x1b                    // branch "n>0"

add   Rseq, Reip, Length(jg)
10   ldc  Rtarg, EIP(target)
      selcc Reip, Rseq, Rtarg
      commit
      jg   mainloop, mainloop

15   Host Instruction key:
      selcc = Select one of the source registers and copy its
            contents to the destination register based on the condition
            codes.

20   The above sample illustrates a next stage of optimization in which a
      speculative translation eliminates the upper memory boundary check
      which is only necessary for unaligned page crossing memory
      references at the top of the memory address space. Failure of this
      assumption is detected by either hardware or software alignment fix
25   up. This reduces the translation by another host primitive instruction
      for each target primitive instruction requiring addressing. This
      optimization requires both the assumption noted before that the
      application utilizes a 32 bit flat memory model and the speculation
      that the instruction is aligned. If these are not both true, then the
30   translation will fail when it is executed; and a new translation will be
      necessary.

      Detect and eliminate redundant address calculations. The example shows the code
      after eliminating the redundant operations.

35   mov  %ecx, [%ebp+0xc]        // load c

      add   R0, Rebp, 0xc
      ld    Recx, [R0]
      add   Reip, Reip, 3
40   commit

```

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```

    mov  %eax, [%ebp+0x8]           // load s

5    add  R2, Rbp, 0x8
    ld   Reax, [R2]
    add  Reip, Reip, 3
    commit

    mov  [%eax], %ecx              // store c into [s]

10   st   [Reax], Recx
    add  Reip, Reip, 2
    commit

    add  %eax, #4                  // increment s by 4

15   addcc Reax, Reax, 4
    add  Reip, Reip, 5
    commit

20   mov  [%ebp+0x8], %eax         // store (s + 4)

    st   [R2], Reax
    add  Reip, Reip, 3

25   commit

    mov  %eax, [%ebp+0x10]         // load n

    add  R7, Rbp, 0x10
30   ld   Reax, [R7]
    add  Reip, Reip, 3
    commit

    lea  %ecx, [%eax-1]           // decrement n

35   sub  Recx, Reax, 1
    add  Reip, Reip, 3
    commit

    mov  [%ebp+0x10], %ecx         // store (n - 1)

    st   [R7], Recx
    add  Reip, Reip, 3
    commit

45   and  %eax, %eax              // test n

    andcc R11, Reax, Reax
    add  Reip, Reip, 3
50   commit

```

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```

jg    .-0x1b                // branch "n>0"

add    Rseq,Reip,Length(jg)
ldc    Rtarg,EIP(target)
5      selcc Reip,Rseq,Rtarg
      commit
      jg    mainloop,mainloop

```

This sample illustrates a next optimization in which common host
 10 expressions are eliminated. More particularly, in translating the
 second target primitive instruction, a value in working register Rebp
 (the working register representing the stack base point register of an
 X86 processor) is added to an offset value 0x8 and placed in a host
 working register R2. It will be noted that the same operation took
 15 place in translating target primitive instruction five in the previous
 sample except that the result of the addition was placed in working
 register R5. Consequently the value to be placed in working register
 R5 already exists in working register R2 when host primitive
 instruction five is about to occur. Thus, the host addition instruction
 20 may be eliminated from the translation of target primitive instruction
 five; and the value in working register R2 copied to working register
 R5. Similarly, a host instruction adding a value in working register
 Rebp to an offset value 0x10 may be eliminated in the translation of
 target primitive instruction eight because the step has already been
 25 accomplished in the translation of target primitive instruction six and
 the result resides in register R7. It should be noted that this
 optimization does not depend on speculation and consequently is not
 subject to failure and retranslation.

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Assume that target exceptions will not occur within the translation so delay updating eip and target state.

```

5      mov    %ecx,[%ebp+0xc]           // load c
      add    R0,Rebp,0xc
      ld     Recx,[R0]

10     mov    %eax,[%ebp+0x8]          // load s
      add    R2,Rebp,0x8
      ld     Reax,[R2]

15     mov    [%eax],%ecx              // store c into [s]
      st     [Reax],Recx

      add    %eax,#4                   // increment s by 4

20     add    Reax,Reax,4

      mov    [%ebp+0x8],%eax           // store (s + 4)
      st     [R2],Reax

25     mov    %eax,[%ebp+0x10]         // load n
      add    R7,Rebp,0x10
      ld     Reax,[R7]

30     lea    %ecx,[%eax-1]            // decrement n
      sub    Recx,Reax,1

35     mov    [%ebp+0x10],%ecx         // store (n - 1)
      st     [R7],Recx

40     and    %eax,%eax                // test n
      andcc  R11,Reax,Reax

      jg     .-0x1b                    // branch "n>0"

45     add    Rseq,Reip,Length(block)
      ldc    Rtarg,EIP(target)
      selcc  Reip,Rseq,Rtarg
      commit
      jg     mainloop,mainloop

```

50

The above sample illustrates an optimization which speculates that the translation of the primitive target instructions making up the entire translation may be accomplished without generating an exception. If this is true, then there is no need to update the official target registers or to commit the uncommitted stores in the store buffer at the end of each sequence of host primitive instructions which carries out an individual target primitive instruction. If the speculation holds true, the official target registers need only be updated and the stores need only be committed once, at the end of the sequence of target primitive instructions. This allows the elimination of two primitive host instructions for carrying out each primitive target instruction. These are replaced by a single host primitive instruction which updates the official target registers and commits the uncommitted stores to memory.

As will be understood, this is another speculative operation which is also highly likely to involve a correct speculation. This step offers a very great advantage over all prior art emulation techniques if the speculation holds true. It allows all of the primitive host instructions which carry out the entire sequence of target primitive instructions to be grouped in a sequence in which all of the individual host primitives may be optimized together. This has the advantage of allowing a great number of operations to be run in parallel on a morph host which takes advantage of the very long instruction word techniques. It also allows a greater number of other optimizations to be made because more choices for such optimizations exist. Once again, however, if the speculation proves untrue and an exception is taken when the loop is executed, the official target registers and memory hold the official

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target state which existed at the beginning of the sequence of target primitive instructions since a commit does not occur until the sequence of host instructions is actually executed. All that is necessary to recover from an exception is to dump the uncommitted stores, rollback the official registers into the working registers, and restart translation of the target primitive instructions at the beginning of the sequence. This re-translation produces a translation of one target instruction at a time, and the official state is updated after the host sequence representing each target primitive instruction has been translated. This translation is then executed. When the exception occurs on this re-translation, correct target state is immediately available in the official target registers and memory for carrying out the exception.

In summary:

```

15      add    R0,Rebp,0xc
        ld     Recx,[R0]
        add    R2,Rebp,0x8
        ld     Reax,[R2]
20      st     [Reax],Recx
        add    Reax,Reax,4
        st     [R2],Reax
        add    R7,Rebp,0x10
        ld     Reax,[R7]           // Live out
25      sub    Recx,Reax,1         // Live out
        st     [R7],Recx
        andcc  R11,Reax,Reax
        add    Rseq,Reip,Length(block)
        ldc    Rtarg,EIP(target)
30      selcc  Reip,Rseq,Rtarg
        commit
        jg     mainloop,mainloop

```

35 The comment "Live Out" refers to the need to actually maintain Reax and Recx correctly prior to the commit. Otherwise further optimization might be possible.

=====

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The summary above illustrates the sequence of host primitive instructions which remain at this point in the optimization process. While this example shows the maintenance of the target instruction pointer (EIP) inline, it is possible to maintain the pointer EIP for branches out of line at translation time, which would remove the pointer EIP updating sequence from this and subsequent steps of the example.

Renaming to reduce register resource dependencies. This will allow subsequent scheduling to be more effective. From this point on, the original target X86 code is omitted as the relationship between individual target X86 instructions and host instructions becomes increasingly blurred.

```

15      add    R0,Rebp,0xc
        ld     R1,[R0]
        add    R2,Rebp,0x8
        ld     R3,[R2]
        st     [R3],R1
        add    R4,R3,4
        st     [R2],R4
20      add    R7,Rebp,0x10
        ld     Reax,[R7]           // Live out
        sub    Recx,Reax,1         // Live out
        st     [R7],Recx
        andcc  R11,Reax,Reax
25      add    Rseq,Reip,Length(block)
        ldc    Rtarg,EIP(target)
        selcc  Reip,Rseq,Rtarg
        commit
        jg     mainloop,mainloop
30

```

This sample illustrates a next step of optimization, normally called register renaming, in which operations requiring working registers used for more than one operation in the sequence of host primitive instructions are changed to utilize a different unused working register to eliminate the possibility that two host instructions will require the same hardware. Thus, for example, the second host primitive instruction in two samples above uses working register Recx which represents an official target register ECX. The tenth host primitive

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instruction also uses the working register Recx. By changing the operation in the second host primitive instruction so that the value pointed to by the address in R0 is stored in the working register R1 rather than the register Recx, the two host instructions do not both use the same register. Similarly, the fourth, fifth, and sixth host primitive instructions all utilize the working register Reax in the earlier sample; by changing the fourth host primitive instruction to utilize the previously unused working register R3 instead the working register Reax and the sixth host primitive instruction to utilize the previously unused working register R4 instead of the register Reax, these hardware dependencies are eliminated.

After the scheduling process which organizes the primitive host operations as multiple operations that can execute in the parallel on the host VLIW hardware. Each line shows the parallel operations that the VLIW machine executes, and the "&" indicates the parallelism.

	add	R2, Rbp, 0x8	& add	R0, Rbp, 0xc
	nop		& add	R7, Rbp, 0x10
	ld	R3, [R2]	& add	Rseq, Reip, Length(block)
20	ld	R1, [R0]	& add	R4, R3, 4
	st	[R3], R1	& ldc	Rtarg, EIP(target)
	ld	Reax, [R7]	& nop	
	st	[R2], R4	& sub	Recx, Reax, 1
	st	[R7], Recx	& andcc	R11, Reax, Reax
25	selcc	Reip, Rseq, Rtarg	& jg	mainloop, mainloop & commit

Host Instruction key:

nop = no operation

30

The above sample illustrates the scheduling of host primitive instructions for execution on the morph host. In this example, the morph host is presumed to be a VLIW processor which in addition to the hardware enhancements provided for cooperating with the code morphing software also includes, among other processing units, two arithmetic and logic (ALU) units. The first line illustrates two

35

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individual add instructions which have been scheduled to run together on the morph host. As may be seen, these are the third and the eight primitive host instructions in the sample just before the summary above. The second line includes a NOP instruction (no operation but go to next instruction) and another add instruction.

The NOP instruction illustrates that there are not always two instructions which can be run together even after some scheduling optimizing has taken place. In any case, this sample illustrates that only nine sets of primitive host instructions are left at this point to execute the original ten target instructions.

resolve host branch targets and chain stored translations

	add R2,Rebp,0x8	& add R0,Rebp,0xc
	nop	& add R7,Rebp,0x10
15	ld R3,[R2]	& add Rseq,Reip,Length(block)
	ld R1,[R0]	& add R4,R3,4
	st [R3],R1	& ldc Rtarg,EIP(target)
	ld Reax,[R7]	& nop
	st [R2],R4	& sub Recx,Reax,1
20	st [R7],Recx	& andcc R11,Reax,Reax
	selcc Reip,Rseq,Rtarg	& jg Sequential,Target & commit

This sample illustrates essentially the same set of host primitive instructions except that the instructions have by now been stored in the translation buffer and executed one or more times because the last jump (jg) instruction now points to a jump address furnished by chaining to another sequence of translated instructions. The chaining process takes the sequence of instructions out of the translator main loop so that translation of the sequence has been completed.

Advanced Optimizations, Backward Code Motion:

This and subsequent examples start with the code prior to scheduling. This optimization first depends on detecting that the code is a loop. Then invariant operations can be moved out of the loop body and executed once before entering the loop body.

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```

entry:
    add    R0,Rebp,0xc
    add    R2,Rebp,0x8
    add    R7,Rebp,0x10
5      add    Rseq,Reip,Length(block)
    ldc    Rtarg,EIP(target)

Loop:
    ld     R1,[R0]
10      ld     R3,[R2]
    st     [R3],R1
    add    R4,R3,4
    st     [R2],R4
    ld     Reax,[R7]
15      sub    Recx,Reax,1
    st     [R7],Recx
    andcc  R11,Reax,Reax
    selcc  Reip,Rseq,Rtarg
    commit
20      jg     mainloop,Loop

```

The above sample illustrates an advanced optimization step which is usually only utilized with sequences which are to be repeated a large number of times. The process first detects translations that form loops, and reviews the individual primitives host instructions to determine which instructions produce constant results within the loop body. These instructions are removed from the loop and executed only once to place a value in a register; from that point on, the value stored in the register is used rather than rerunning the instruction.

30 **Schedule the loop body after backward code motion.** For example purposes, only the code in the loop body is shown scheduled

```

Entry:
    add    R0,Rebp,0xc
35      add    R2,Rebp,0x8
    add    R7,Rebp,0x10
    add    Rseq,Reip,Length(block)
    ldc    Rtarg,EIP(target)

40      Loop:
    ld     R3,[R2]           & nop
    ld     R1,[R0]           & add R4,R3,4
    st     [R3],R1           & nop
    ld     Reax,[R7]         & nop
45      st     [R2],R4       & sub Recx,Reax,1

```

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```

st      [R7],Recx      & andcc R11,Reax,Reax
selcc Reip,Rseq,Rtarg  & jg  Sequential,Loop  & commit

```

Host Instruction key:

5 ldc = load a 32-bit constant

When these non-repetitive instructions are removed from the loop and the sequence is scheduled for execution, the scheduled instructions appear as in the last sample above. It can be seen that the initial
 10 instructions are performed but once during the first iteration of the loop and thereafter only the host primitive instructions remaining in the seven clock intervals shown are executed during the loop. Thus, the execution time has been reduced to seven instruction intervals from the ten instructions necessary to execute the primitive target
 15 instructions.

As may be seen, the steps which have been removed from the loop are address generation steps. Thus, address generation only need be done once per loop invocation in the improved microprocessor; that is, the address generation need only be done one time. On the other
 20 hand, the address generation hardware of the X86 target processor must generate these addresses each time the loop is executed. If a loop is executed one hundred times, the improved microprocessor generates the addresses only once while a target processor would generate each address one hundred times.

25 **After Backward Code Motion:**

Target:

```

add     R0,Rebp,0xc
add     R2,Rebp,0x8
30      add     R7,Rebp,0x10
add     Rseq,Reip,Length(block)
ldc     Rtarg,EIP(target)

```

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Loop:

```

      ld    R1, [R0]
      ld    R3, [R2]
      st    [R3], R1
5      add  R4, R3, 4
      st    [R2], R4
      ld    Reax, [R7]           //Live out
      sub   Recx, Reax, 1        //Live out
      st    [R7], Recx
10     andcc R11, Reax, Reax
      selcc Reip, Rseq, Rtarg
      commit
      jg    mainloop, Loop

```

=====

15 Register Allocation:

20 This shows the use of register alias detection hardware of the morph host that allows variables to be safely moved from memory into registers. The starting point is the code after "backward code motion". This shows the optimization that can eliminate loads.

25 First the loads are performed. The address is protected by the alias hardware, such that should a store to the address occur, an "alias" exception is raised. The loads in the loop body are then replaced with copies. After the main body of the loop, the alias hardware is freed.

Entry:

```

30     add   R0, Rbp, 0xc
      add   R2, Rbp, 0x8
      add   R7, Rbp, 0x10
      add   Rseq, Reip, Length(block)
      ldc   Rtarg, EIP(target)

35     ld    Rc, [R0]           ;First do the load of the variable from
memory                                prot    [R0], Alias1 ;Then protect the memory location from
stores                                stores

40     ld    Rs, [R2]
      prot   [R2], Alias2

      ld    Rn, [R7]
      prot   [R7], Alias3
45

```

Loop:

```

      copy   R1, Rc
      copy   R3, Rs
      st     [R3], R1
50     add   R4, Rs, 4

      copy   Rs, R4
      st     [R2], Rs, NoAliasCheck
      copy   Reax, Rn           //Live out
55     sub    Recx, Reax, 1      //Live out
      copy   Rn, Recx

```

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```

    st      [R7],Rn,noAliasCheck
    andcc   R11,Reax,Reax
    selcc   Reip,Rseq,Rtarg
    commit
5         jg      Epilog,Loop

Epilog:
    FA      Alias1      Free the alias detection hardware
    FA      Alias2      Free the alias detection hardware
10         FA      Alias3      Free the alias detection hardware
    j       Sequential

Host Instruction key:
    protect = protect address from loads      FA = free alias
15         copy = copy          j = jump

```

This sample illustrates an even more advanced optimization which may be practiced by the microprocessor including the present invention. Referring back to the second sample before this sample, it

20 will be noticed that the first three add instructions involved computing addresses on the stack. These addresses do not change during the execution of the sequence of host operations. Consequently, the values stored at these addresses may be retrieved from memory and loaded in registers where they are immediately available for execution.

25 As may be seen, this is done in host primitive instructions six, eight, and ten. In instructions seven, nine and eleven, each of the memory addresses is marked as protected by special host alias hardware and the registers are indicated as aliases for those memory addresses so that any attempt to vary the data will cause an exception. At this

30 point, each of the load operations involving moving data from these stack memory addresses becomes a simple register-to-register copy operation which proceeds much faster than loading from a memory address. It should be noted that once the loop has been executed until $n=0$, the protection must be removed from each of the memory

35 addresses so that the alias registers may be otherwise utilized.

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Copy Propagation :

After using the alias hardware to turn loads within the loop body into copies, copy propagation allows the elimination of some copies.

```

5      Entry:
          add    R0,Rebp,0xc
          add    R2,Rebp,0x8
          add    R7,Rebp,0x10
10         add    Rseq,Reip,Length(block)
          ldc    Rtarg,EIP(target)

          ld     Rc,[R0]
          prot   [R0],Alias1
15         ld     Rs,[R2]
          prot   [R2],Alias2

          ld     Recx,[R7]
          prot   [R7],Alias3
20

      Loop:
          st     [Rs],Rc
          add    Rs,Rs,4
25         st     [R2],Rs,NoAliasCheck
          copy   Reax,Recx                //Live out

          sub    Recx,Reax,1              //Live out
          st     [R7],Recx,NoAliasCheck
30         andcc  R11,Reax,Reax
          selcc  Reip,Rseq,Rtarg
          commit
          jg     Epilog,Loop

35      Epilog:
          FA     Alias1
          FA     Alias2
          FA     Alias3
          j      Sequential
40

```

This sample illustrates the next stage of optimization in which it is recognized that most of the copy instructions which replaced the load instructions in the optimization illustrated in the last sample are unnecessary and may be eliminated. That is, if a register-to-register

45 copy operation takes place, then the data existed before the operation in the register from which the data was copied. If so, the data can be accessed in the first register rather than the register to which it is

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being copied and the copy operation eliminated. As may be seen, this eliminates the first, second, fifth, and ninth primitive host instructions shown in the loop of the last sample. In addition, the registers used in others of the host primitive instructions are also

5 changed to reflect the correct registers for the data. Thus, for example, when the first and second copy instructions are eliminated, the third store instruction must copy the data from the working register Rc where it exists (rather than register R1) and place the data at the address indicated in working register Rs where the address

10 exists (rather than register R3).

Example illustrating scheduling of the loop body only .

```

Entry:
    add    R0,Rebp,0xc
15      add    R2,Rebp,0x8
    add    R7,Rebp,0x10
    add    Rseq,Reip,Length(block)
    ldc    Rtarg,EIP(target)

    ld      Rc,[R0]
20      prot   [R0],Alias1

    ld      Rs,[R2]
    prot    [R2],Alias2
25

    ld      Recx,[R7]
    prot    [R7],Alias3

Loop:
    st      [Rs],Rc,          & add Rs,Rs,4      & copy
30      Reax,Recx
    st      [R2],Rs,NAC       & sub Recx,Reax,1
    st      [R7],Recx,NAC     & andcc R11,Reax,Reax
    selcc   Reip,Rseq,Rtarg   & jg  Epilog,Loop & commit

Epilog:
35      FA     Alias1
    FA     Alias2
    FA     Alias3
    j       Sequential

40      Host Instruction key:
    NAC= No Alias Check
  
```

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The scheduled host instructions are illustrated in the sample above. It will be noted that the sequence is such that fewer clocks are required to execute the loop than to execute the primitive target instruction originally decoded from the source code. Thus, apart from
 5 all of the other acceleration accomplished, the total number of combined operations to be run is simply less than the operations necessary to execute the original target code.

Store Elimination by use of the alias hardware .

```

10  Entry:
      add    R0,Rebp,0xc
      add    R2,Rebp,0x8
      add    R7,Rebp,0x10
      add    Rseq,Reip,Length(block)
15      ldc    Rtarg,EIP(target)

      ld      Rc,[R0]
      prot    [R0],Alias1      ;protect the address from loads
and stores

20      ld      Rs,[R2]
      prot    [R2],Alias2      ;protect the address from loads
and stores

25      ld      Recx,[R7]
      prot    [R7],Alias3      ;protect the address from loads
and stores

Loop:
30      st      [Rs],Rc,      & add Rs,Rs,4      & copy
      Reax,Recx
      sub      Recx,Reax,1    & andcc R11,Reax,Reax
      selcc    Reip,Rseq,Rtarg & jg  Epilog,Loop & commit
      Epilog:

35      FA      Alias1
      FA      Alias2
      FA      Alias3
      st      [R2],Rs        ;writeback the final value of Rs
      st      [R7],Recx      ;writeback the final value of
40      Recx
      j        Sequential
  
```

The final optimization shown in this sample is the use of the alias hardware to eliminate stores. This eliminates the stores from within

the loop body, and performs them only in the loop epilog. This reduces the number of host instructions within the loop body to three compared to the original ten target instructions.

Although the present invention has been described in terms of a preferred embodiment, it will be appreciated that various
5 modifications and alterations might be made by those skilled in the art without departing from the spirit and scope of the invention. For example, although the invention has been described with relation to the emulation of X86 processors, it should be understood that the
10 invention applies just as well to programs designed for other processor architectures, and programs that execute on virtual machines, such as P code, Postscript, or Java programs. The invention should therefore be measured in terms of the claims which follow.

What Is Claimed Is:

Claim 1. A system for controlling access to memory in a computer comprising

hardware means for indicating whether an address of an instruction is directed to memory or to a memory mapped I/O device,

5 software means for initiating an instruction speculating that the address is memory or I/O,

means for comparing the speculation made with respect to the instruction with an indication of the hardware means, and

means for taking a corrective action if a comparison shows that the
10 speculation and the indication differ.

Claim 2. A system for controlling access to memory as in Claim 1 in which the hardware means comprises:

a look-aside buffer including a plurality of storage locations for virtual addresses and associated physical addresses, and

5 a storage position in each storage location of the translation look aside buffer.

Claim 3. A system for controlling access to memory as in Claim 1 in which the software means for initiating an instruction speculating that the address is memory or I/O is a set of instructions for a host processor translated from a set of instructions for a target processor,

5 the set of instructions including an indication of a speculation for each address used by the instruction.

Claim 4. A system for controlling access to memory as in Claim 1 in which the hardware means comprises:

a look-aside buffer including a plurality of storage locations for virtual addresses and associated physical addresses, and

5 a storage position in each storage location of the translation look aside buffer; and

in which the software means for initiating an instruction speculating that the address is memory or I/O is a set of instructions for a host processor translated from a set of instructions for a target processor,
10 the set of instructions including an indication of a speculation for each address used by the instruction.

Claim 5. A system for controlling access to memory as in Claim 4 in which the means for comparing the speculation made with respect to the instruction with an indication of the hardware means comprises a hardware comparator for comparing the an indication of a
5 speculation for each address with a condition of a storage position in a storage location storing a matching address.

Claim 6. A memory controller for a microprocessor comprising:

means to both detect a failure of speculation on the nature of the memory being addressed, and

means to recover from such a failure.

Claim 7. A memory controller as claimed in Claim 6 in which the means to detect a failure of speculation on the nature of the memory being addressed comprises

hardware means for storing an indication of the nature of the physical
5 memory being addressed, and

means for comparing a speculation on the nature of the memory being
addressed and an indication of the nature of the physical memory
being addressed stored by the hardware means.

Claim 8. A memory controller as claimed in Claim 7 in which the
means to recover from such failures comprises:

means responsive to a failure of a comparison by the means for
comparing a speculation on the nature of the memory being addressed
5 and an indication of the nature of the physical memory being
addressed for generating an exception, and

means for responding to the exception.

Claim 9. A memory controller as claimed in Claim 6 in which the
means to detect a failure of speculation on the nature of the memory
being addressed comprises

hardware means for storing an indication of the nature of the
5 physical memory being addressed, and

means for comparing a speculation on the nature of the memory
being addressed and an indication of the nature of the physical
memory being addressed stored by the hardware means; and

in which the means to recover from such failures comprises:

10 means responsive to a failure of a comparison by the means for
comparing a speculation on the nature of the memory being

addressed and an indication of the nature of the physical memory being addressed for generating an exception, and means for responding to the exception.

Claim 10. A memory controller as claimed in Claim 9 in which the means for responding to the exception comprises:

means for recovering state of a computer utilizing the microprocessor, and

- 5 means for accessing the address presuming the nature of the memory being addressed is different than the speculation.

Claim 11. A memory controller as claimed in Claim 9 in which the means to recover from such a failure comprises:

means for generating an exception in response to a failure of speculation on the nature of the memory being addressed,

- 5 means for providing a process for recovering from an exception related to a failure of the speculation on the nature of the memory being addressed.

Claim 12. A memory control system for a computer comprising:

main memory,

memory-mapped input/output (I/O) devices,

memory control software for causing commands to affect operations at

- 5 particular addresses,

a translation lookaside buffer including memory locations for storing virtual addresses which have been recently accessed and translations of those virtual addresses to physical addresses within the computer,

at least one memory position for each memory location recording an indication whether the address is assumed to be memory or memory-mapped I/O.

Claim 13. A memory control system as claimed in Claim 12 further comprising a comparator for detecting whether an instruction accessing a virtual address stored in the translation lookaside buffer presumes that the physical address is the same as the indication recorded for the physical address.

Claim 14. A method of recovering from a failed speculation regarding a property of components accessed as memory in a computer system comprising the steps of:

providing a process for recovering from an exception related to a failure of the existence of a property of components accessed as memory,

generating an access to an address speculating on a property of a particular address,

detecting failure of the speculation by comparing the speculation to the property of the component addressed, and

responding to detection of a failure of the speculation by running the process.

Claim 15. A method of recovering from a failed speculation as claimed in Claim 14 in which the step of detecting failure of the speculation includes generating an exception in response to the failure of the speculation.

Claim 16. A method of recovering from a failed speculation as claimed in Claim 14

in which the step of providing a process for recovering from an exception related to a failure of the existence of a property of

5 components accessed as memory comprises:

storing an exception handler for recovering storing an indication of state of the computer system existing prior to the speculation, and

10 storing an indication of state of the computer system existing prior to the speculation; and

in which the step of responding to detection of a failure of the speculation by running the process comprises:

recovering the stored indication of state, and

15 continuing with the operation of the computer utilizing the recovered state from the point at which the failed speculation was taken.

Claim 17. A microprocessor comprising:

a host processor capable of executing a first instruction set,

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code morphing software for translating programs written for a target processor having a second different instruction set into instructions of
5 the first instruction set, and

a memory controller comprising

an address translation buffer including a plurality of storage locations in which recently accessed virtual target addresses and physical addresses represented by the virtual target
10 addresses are to be recorded,

each of the storage locations including means for indicating whether a physical address is a memory address or a memory-mapped input/output (I/O) address; and

15 means for comparing an indication in a storage location with a speculation made that an access to a virtual target address in a storage location is to memory or memory-mapped I/O to indicate a subsequent operation to be taken in accessing the address.

Claim 18. A microprocessor as claimed in Claim 17 in which the
means for comparing an indication in a storage location with a speculation made that an access to a virtual target address in a storage location is to memory or memory-mapped I/O to indicate a
5 subsequent operation taken in accessing the address comprises
means for generating an exception in response to a failure of a comparison, and

means for responding to the exception to indicate a subsequent operation to be taken in accessing the address.

Claim 19. A microprocessor as claimed in Claim 18 in which the means for indicating whether a physical address is a memory address or a memory-mapped input/output (I/O) address comprises a storage position in a storage location.

Claim 20. A memory controller comprising

an address translation buffer including a plurality of storage locations in which recently accessed virtual addresses and physical addresses represented by the virtual addresses are to be recorded,

5 each of the storage locations including means for indicating whether a physical address is a memory address or a memory-mapped input/output (I/O) address; and

means for comparing an indication in a storage location with a speculation made that an access to an address in a storage location is
10 to memory or memory-mapped I/O to indicate a subsequent operation taken in accessing the address.

Claim 21. A memory controller as claimed in Claim 20 in which the means for comparing an indication in a storage location with a speculation made that an access to a virtual target address in a storage location is to memory or memory-mapped I/O to indicate a
5 subsequent operation taken in accessing the address comprises means for generating an exception in response to a failure of a comparison, and

means for responding to the exception to indicate a subsequent operation to be taken in accessing the address.

Claim 22. A memory controller as claimed in Claim 20 in which the means for indicating whether a physical address is a memory address or a memory-mapped input/output (I/O) address comprises a storage position in a storage location.

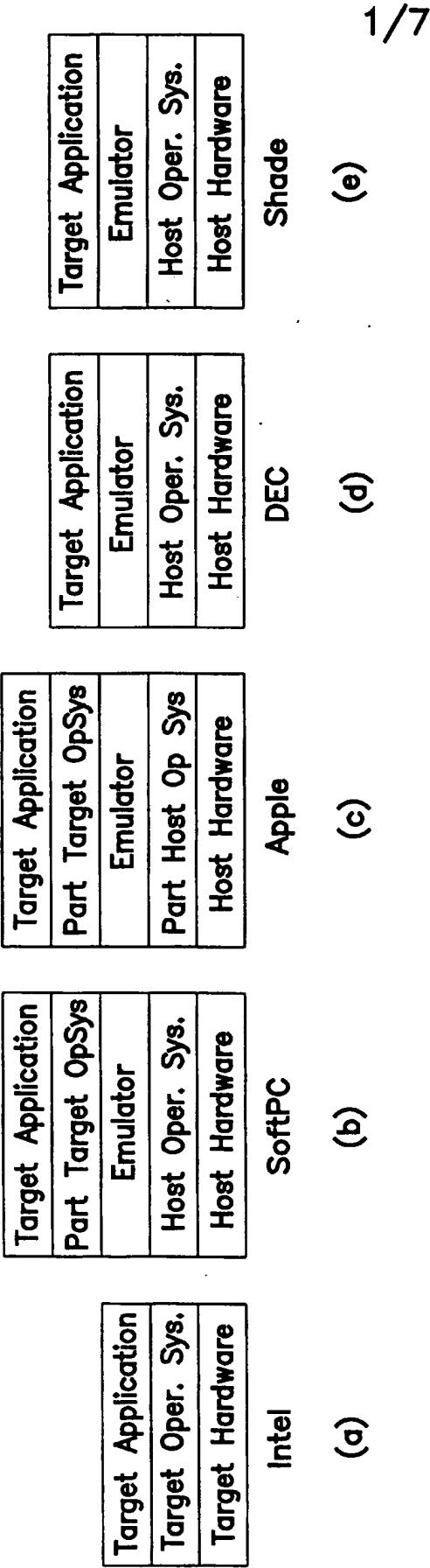


Figure 1

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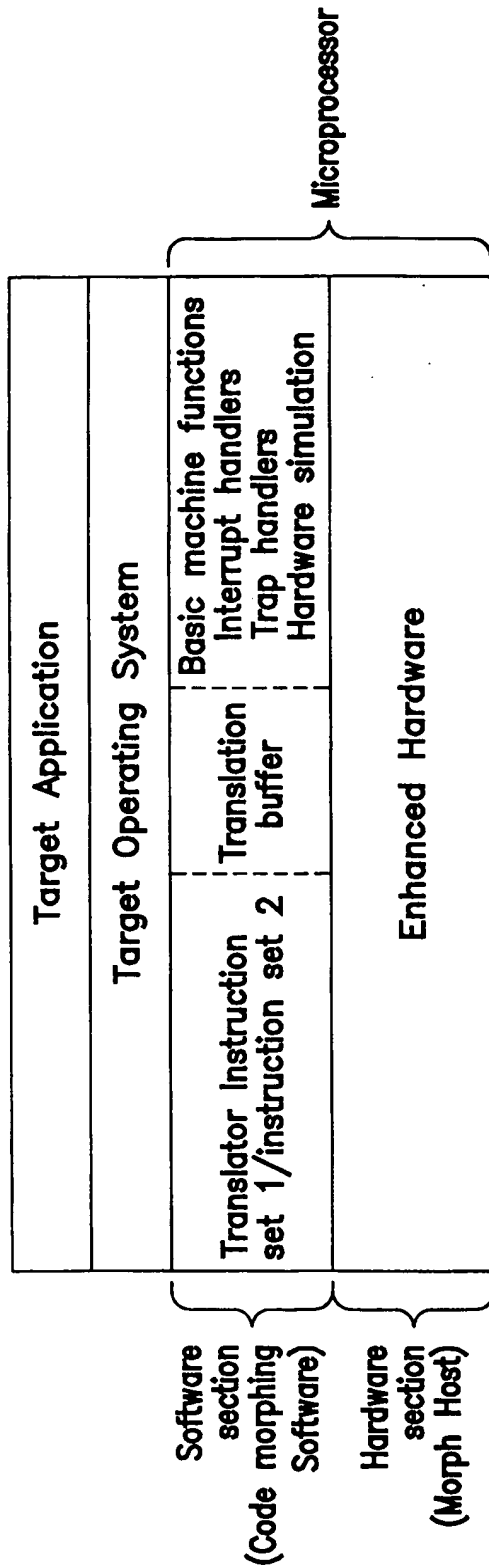


Figure 2

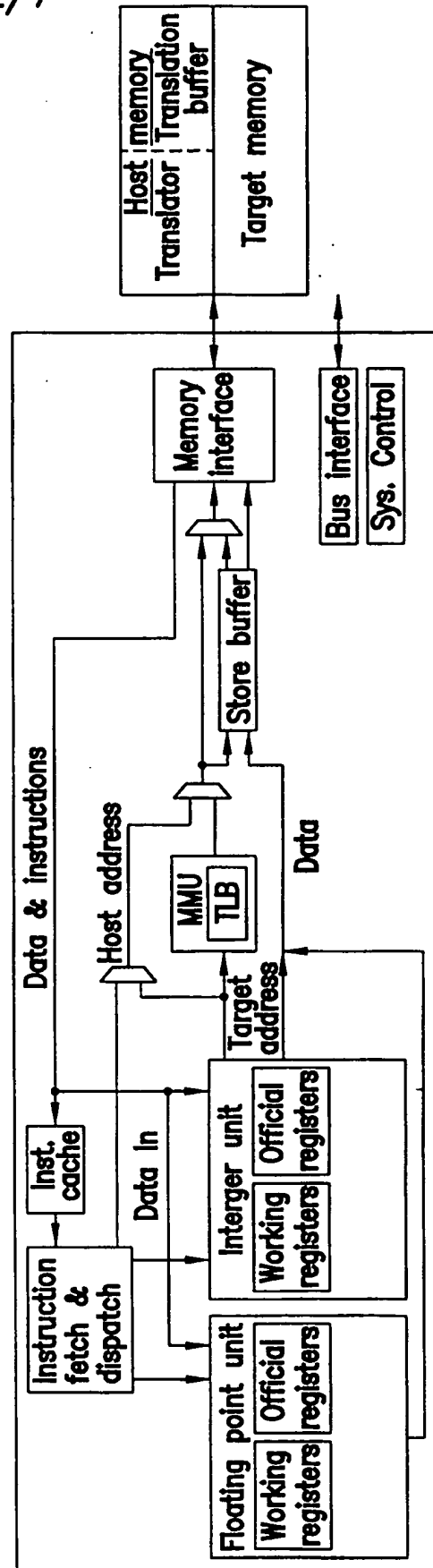


Figure 3

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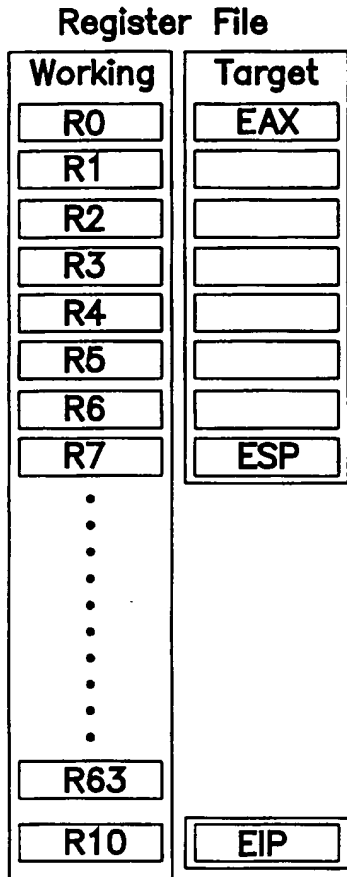


Figure 4

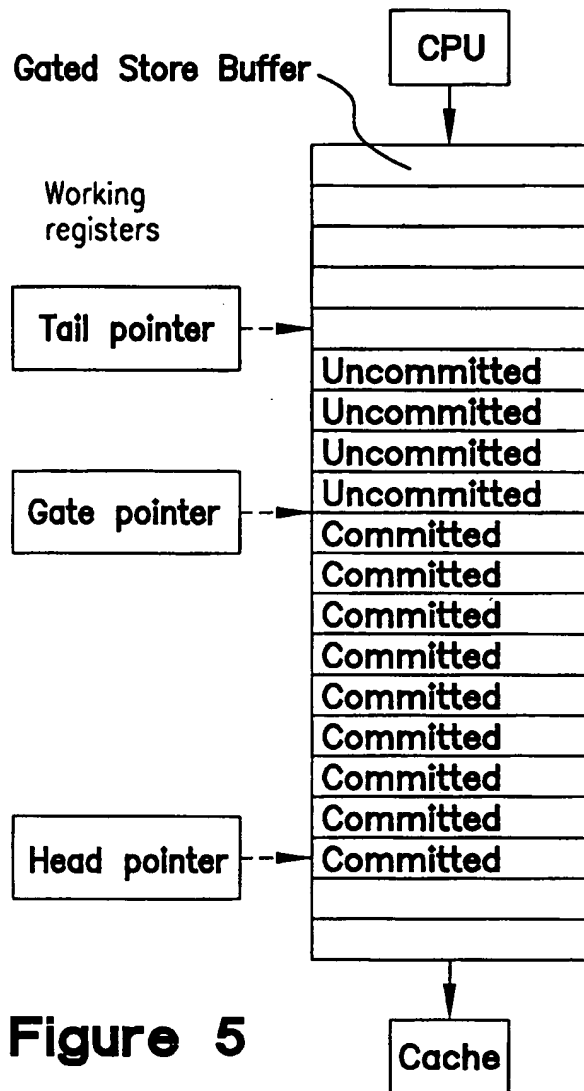


Figure 5

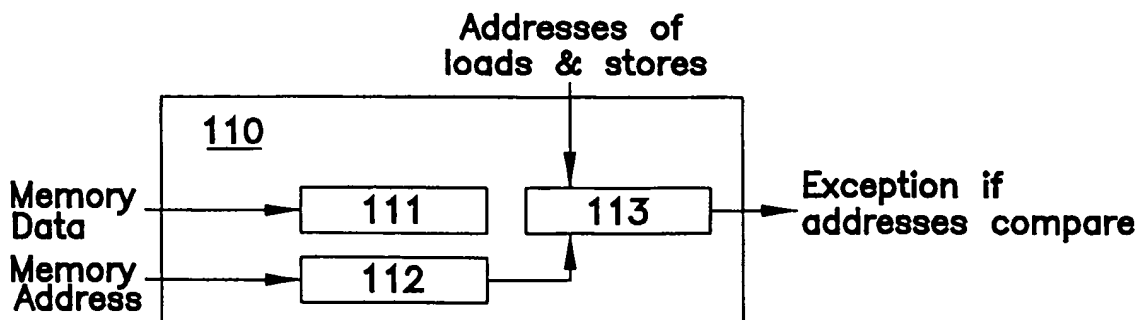
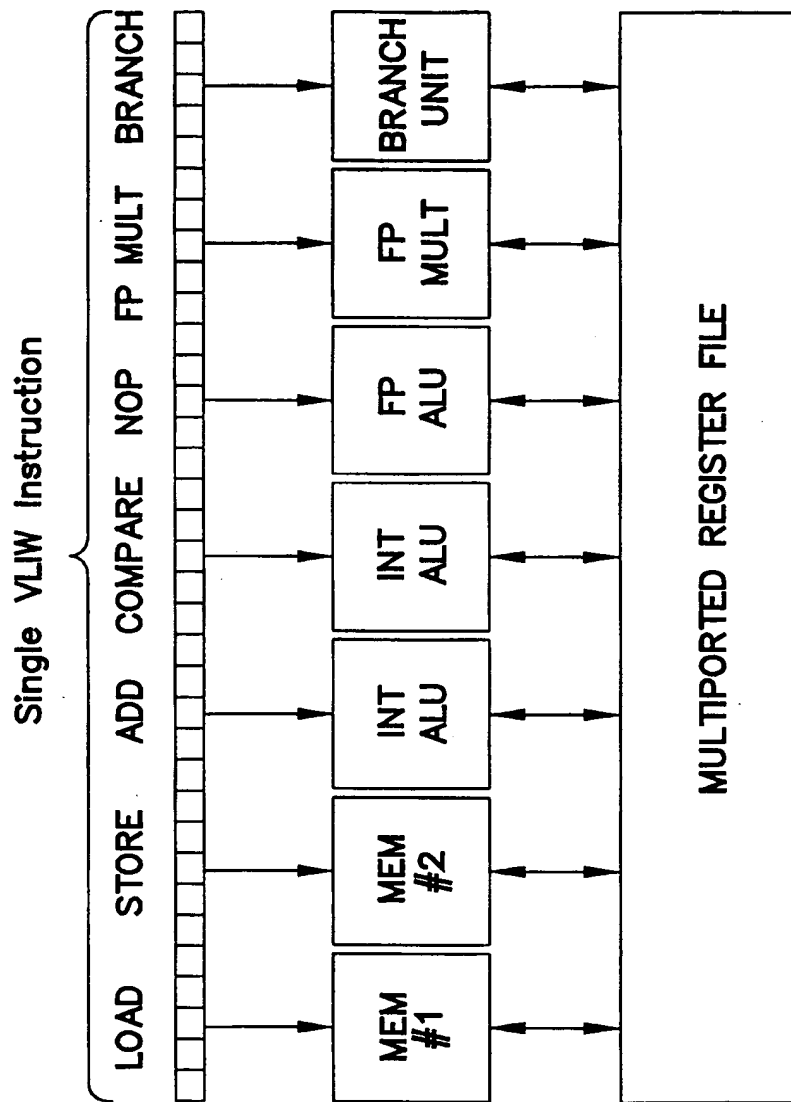


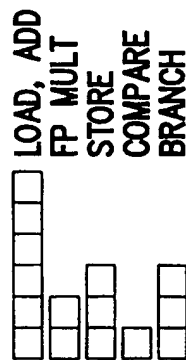
Figure 10

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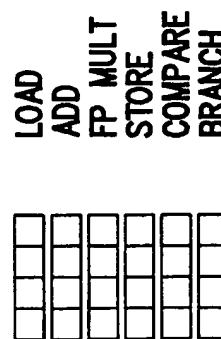


(c)

Figure 6



(a)



(b)